



# TLK72 B

## MICROPROCESSOR-BASED DIGITAL ELECTRONIC CONTROLLER



### OPERATING INSTRUCTIONS

14/04 - Code: ISTR\_M\_TLK72B\_E\_03\_--

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### FOREWORD



This manual contains the information necessary for the product to be installed correctly and also instructions for its maintenance and use; we therefore recommend that the utmost attention is paid to the following instructions and to save it.

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### INDEX

- 1 **INSTRUMENT DESCRIPTION**
  - 1.1 GENERAL DESCRIPTION
  - 1.2 FRONT PANEL DESCRIPTION
- 2 **PROGRAMMING**
  - 2.1 FAST PROGRAMMING OF SET POINT
  - 2.2 PARAMETER PROGRAMMING
  - 2.3 PARAMETER PROGRAMMING LEVELS
- 3 **INFORMATION ON INSTALLATION AND USE**
  - 3.1 PERMITTED USE
  - 3.2 MECHANICAL MOUNTING
  - 3.3 ELECTRICAL CONNECTIONS
  - 3.4 ELECTRICAL WIRING DIAGRAM
- 4 **FUNCTIONS**
  - 4.1 MEASURING AND VISUALIZATION
  - 4.2 OUTPUTS CONFIGURATION
  - 4.3 ON/OFF CONTROL
  - 4.4 NEUTRAL ZONE ON/OFF CONTROL
  - 4.5 SINGLE ACTION PID CONTROL
  - 4.6 DOUBLE ACTION PID CONTROL
  - 4.7 AUTOTUNING FUNCTION
  - 4.8 REACHING OF SET POINT AT CONTROLLED SPEED
  - 4.9 ALARM OUTPUT FUNCTIONS
  - 4.10 PARAMETERS CONFIGURATION BY A01
- 5 **PROGRAMMABLE PARAMETERS TABLE**
- 6 **PROBLEMS, MAINTENANCE AND WARRANTY**
  - 6.1 ERROR SIGNALLING
  - 6.2 CLEANING
  - 6.3 WARRANTY AND REPAIRS
- 7 **TECHNICAL DATA**
  - 7.1 ELECTRICAL DATA
  - 7.2 MECHANICAL DATA
  - 7.3 DIMENSIONS, PANEL CUT-OUT AND MOUNTING
  - 7.4 FUNCTIONAL DATA
  - 7.5 MEASUREMENT RANGE TABLE
  - 7.6 INSTRUMENT ORDERING CODE

### 1 - INSTRUMENT DESCRIPTION

#### 1.1 - GENERAL DESCRIPTION

TLK 72 B is a digital microprocessor-based controller, with ON/OFF, Neutral Zone ON/OFF, PID single action, PID dual action (direct and reverse) control and with **AUTOTUNING** function (FAST or OSCILLATING type).

The process value is visualized on 4 red displays, while the output status is indicated by 2 LED displays.

The instrument is equipped with a 3 LED programmable shift indexes and can have up to 2 outputs: relay type or can drive solid state relays type (SSR).

Depending on the model required the input accept:

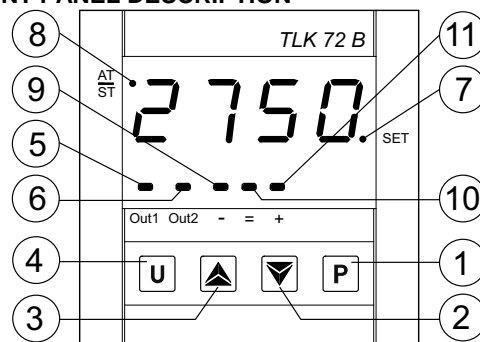
**C:** Thermocouples temperature probes (J, K, S and Ascon Tecnologic ZIS Infrared sensors), mV signals (0... 50/60 mV, 12... 60 mV), Thermoresistances PT100.

**E:** Thermocouples temperature probes (J, K, S and Ascon Tecnologic ZIS Infrared sensors), mV signals (0... 50/60 mV, 12... 60 mV), Thermistors PTC and NTC.

**I:** normalized analogue signals 0/4... 20 mA

**V:** normalized analogue signals 0... 1 V, 0/1... 5 V, 0/2... 10 V

#### 1.2 - FRONT PANEL DESCRIPTION



**11 - Led + Shift index:** indicates that the process value is higher than [SP1+AdE].

The Set Point “SP1” and the alarm threshold “AL1” will only be visible on the Set Point fast programming level (described in par. 2.1) if are present in the menu “OPeR”).

### 3 - INFORMATION ON INSTALLATION AND USE



#### 3.1 - PERMITTED USE

The instrument has been projected and manufactured as a measuring and control device to be used according to EN61010-1 for the altitudes operation until 2000 ms.

The use of the instrument for applications not expressly permitted by the above mentioned rule must adopt all the necessary protective measures.

The instrument CAN NOT be used in dangerous environments (flammable or explosive) without adequate protection.

The installer must ensure that EMC rules are respected, also after the instrument installation, if necessary using proper filters.

Whenever a failure or a malfunction of the device may cause dangerous situations for persons, thing or animals, please remember that the plant has to be equipped with additional devices which will guarantee safety.

#### 3.2 – MECHANICAL MOUNTING

The instrument, in DIN case 72 x 72 mm, is designed for flush-in panel mounting.

Make a hole 66,5 x 66,5 mm and insert the instrument, fixing it with the provided special brackets.

We recommend that the gasket is mounted in order to obtain the front protection degree as declared. Avoid placing the instrument in environments with very high humidity levels or dirt that may create condensation or introduction of conductive substances into the instrument.

Ensure adequate ventilation to the instrument and avoid installation in containers that house devices which may overheat or which may cause the instrument to function at a higher temperature than the one permitted and declared.

Connect the instrument as far away as possible from sources of electromagnetic disturbances such as motors, power relays, relays, solenoid valves, etc.

#### 3.3 - ELECTRICAL CONNECTION

Carry out the electrical wiring by connecting only one wire to each terminal, according to the following diagram, checking that the power supply is the same as that indicated on the instrument and that the load current absorption is no higher than the maximum electricity current permitted.

As the instrument is built-in equipment with permanent connection inside housing, it is not equipped with either switches or internal devices to protect against overload of current: the installation will include an overload protection and a two-phase circuit-breaker, placed as near as possible to the instrument, and located in a position that can easily be reached by the user and marked as instrument disconnecting device which interrupts the power supply to the equipment.

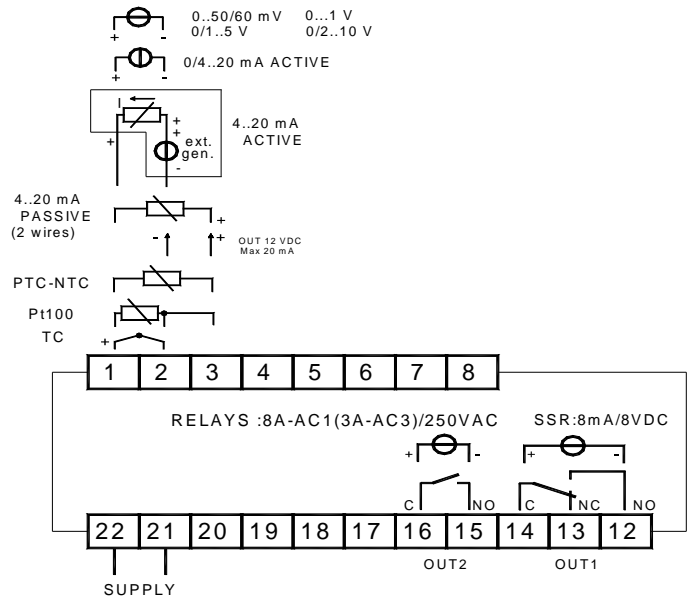
It is also recommended that the supply of all the electrical circuits connected to the instrument must be protect properly, using devices (ex. fuses) proportionate to the circulating currents.

It is strongly recommended that cables with proper insulation, according to the working voltages and temperatures, be used.

Furthermore, the input cable of the probe has to be kept separate from line voltage wiring. If the input cable of the probe is screened, it has to be connected to the ground with only one side.

We recommend that a check should be made that the parameters are those desired and that the application functions correctly before connecting the outputs to the actuators so as to avoid malfunctioning that may cause irregularities in the plant that could cause damage to people, things or animals.

#### 3.4 - ELECTRICAL WIRING DIAGRAM



### 4 - FUNCTIONS

#### 4.1 - MEASURING AND VISUALIZATION

All the parameters referring measurements are contained in the group "InP".

Depending on the model required the input accept:

**C:** Thermocouples temperature probes (J,K,S and Ascon Tecnologic ZIS Infrared sensors), mV signals (0... 50/60 mV, 12... 60 mV), Thermoresistances Pt100.

**E:** Thermocouples temperature probes (J,K,S and Ascon Tecnologic ZIS Infrared sensors), mV signals (0... 50/60 mV, 12... 60 mV), Thermistors PTC and NTC.

**I:** normalized analogue signals 0/4... 20 mA

**V:** normalized analogue signals 0... 1 V, 0/1... 5 V, 0/2... 10 V

Depending on the model, using par. "SEnS", it's possible to select the type of input probe, which can be :

- for thermocouples J (J), K (CrAl), S (S) or for infrared sensors serie Ascon Tecnologic ZIS with linearization J (Ir.J) or K (Ir.CA)

- for thermoresistances Pt100 IEC (Pt1) or thermistors PTC KTY81-121 (Ptc) or NTC 103AT-2 (ntc)

- for normalised signals in current 0... 20 mA (0.20) or 4... 20 mA (4.20)

- for normalised signals in tension 0... 1 V (0.1), 0... 5 V (0.5), 1... 5 V (1.5), 0... 10 V (0.10) or 2... 10 V (2.10).

- for normalised signals in tension 0... 50 mV (0.50), 0... 60 mV (0.60), 12... 60 mV (12.60).

We recommend to switch on and off the instrument when these parameters are modified, in order to obtain a correct measuring.

For the instruments with input for temperature probes (tc, rtd) it's possible to select, through par. "Unit", the unit of measurement (°C,°F) and, through par. "dP" (Pt100, PTC and NTC only) the desired resolution (0=1°; 1=0,1°).

Instead, with regards to the instruments with normalised analogue input signals, it is first necessary to program the desired resolution on par. "dP" (0=1; 1=0,1; 2=0,01; 3=0,001) and then, on par. "SSC", the value that the instrument must visualise at the beginning of the scale (0/4 mA, 0/12 mV, 0/1 V o 0/2 V) and, on par. "FSC", the value that the instrument must visualise at the end of the scale (20 mA, 50 mV, 60 mV, 5 V or 10 V).

The instrument allows for measuring calibration, which may be used to recalibrate the instrument according to application needs, by using par. "OFSt" and "rot".

Programming par. "rot"=1,000, in par. "OFSt" it is possible to set a positive or negative offset that is simply added to the value read by the probe before visualisation, which remains constant for all the measurements.

If instead, it is desired that the offset set should not be constant for all the measurements, it is possible to operate the calibration on any two points.

In this case, in order to decide which values to program on par. "OFSt" and "rot", the following formulae must be applied :

$$\text{"rot"} = (D2-D1) / (M2-M1) \quad \text{"OFSt"} = D2 - (\text{"rot"} \times M2)$$

where:

M1 = measured value 1

D1 = visualisation value when the instrument measures M1

M2 = measured value 2

D2 = visualisation value when the instrument measures M2

It then follows that the instrument will visualise :

$$DV = MV \times \text{"rot"} + \text{"OFSt"}$$

where: DV = visualised value MV = measured value

**Example 1:** It is desired that the instrument visualises the value effectively measured at 20° but that, at 200°, it visualises a value lower than 10° (190°).

Therefore: M1=20 ; D1=20 ; M2=200 ; D2=190

$$\text{"rot"} = (190 - 20) / (200 - 20) = 0,944$$

$$\text{"OFSt"} = 190 - (0,944 \times 200) = 1,2$$

**Example 2:** It is desired that the instrument visualises 10° whilst the value actually measured is 0°, but, at 500° it visualises a 50° higher value (550°).

Therefore: M1=0 ; D1=10 ; M2=500 ; D2=550

$$\text{"rot"} = (550 - 10) / (500 - 0) = 1,08$$

$$\text{"OFSt"} = 550 - (1,08 \times 500) = 10$$

By using par. "FIL" it is possible to program time constant of the software filter for the input value measured, in order to reduce noise sensitivity (increasing the time of reading).

In case of measurement error, the instrument supplies the power as programmed on par. "OPE".

This power will be calculated according to cycle time programmed for the PID controller, while for the ON/OFF controllers the cycle time is automatically considered to be equal to 20 s (e.g. In the event of probe error with ON/OFF control and "OPE"=50, the control output will be activated for 10 s, then it will be deactivated for 10 s and so on until the measurement error remains.).

In the group "lPan" the par. "AdE" is present that defines the 3 led shift index functioning.

The lighting up of the green led = indicates that the process value is within the range [SP1+AdE... SP1-AdE], the lighting up of the led - indicates that the process value is lower than [SP1-AdE] and the lighting up of the led + indicates that the process value is higher than [SP1+AdE].

## 4.2 - OUTPUTS CONFIGURATION

The instrument's outputs can be programmed by entering the group of parameters "Out, where the relative parameters "O1F" and "O2F" (depending on the number of outputs available on the instrument) are located.

The outputs can be set for the following functions :

- Main control output (1.rEG)
- Secondary control output (2.rEG)
- Alarm output normally open (ALno)
- Alarm output normally closed (ALnc)
- Alarm output normally closed with led reverse indication (ALni)
- Output deactivated (OFF)

The coupling outputs number outputs – number alarms can be made in the group referring to the alarm to the alarm ("lAL1").

## 4.3 - ON/OFF CONTROL (1.rEG)

All the parameters referring to the ON/OFF control are contained in the group "l.rEG".

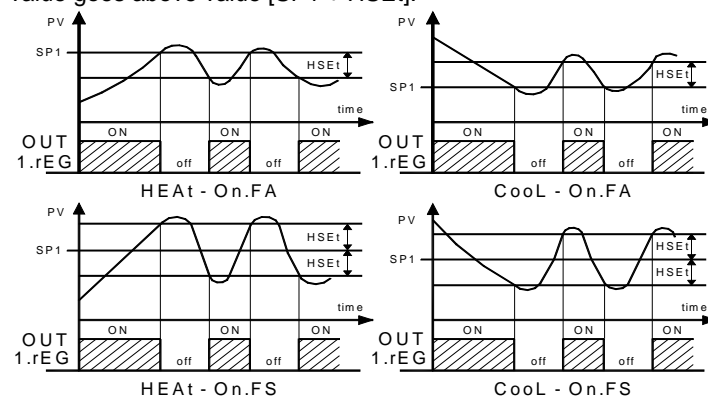
This type of control can be obtained by programming par. "Cont" = On.FS or = On.FA and works on the output programmed as 1.rEG, depending on the measure, on the Set Point "SP1", on the functioning mode "Func" and on the hysteresis "HSEt".

The instrument carries out an ON/OFF control with symmetric hysteresis if "Cont" = On.FS or with asymmetrical hysteresis if "Cont" = On.FA.

The control works in the following way: in the case of reverse action, or heating ("Func"=HEAt), it deactivates the output, when the process value reaches [SP1 + HSEt] in case of symmetrical hysteresis, or [SP1] in case of asymmetrical hysteresis and is then

activated again when the process value goes below value [SP1 - HSEt].

Vice versa, in case of direct action or cooling ("Func"=CooL), it deactivates the output, when the process value reaches [SP1 - HSEt] in case of symmetrical hysteresis, or [SP1] in case of asymmetrical hysteresis and is activated again when the process value goes above value [SP1 + HSEt].



## 4.4 - NEUTRAL ZONE ON/OFF CONTROL (1.rEG - 2.rEG)

All the parameters referring to Neutral Zone ON/OFF control are contained in the group "l.rEG".

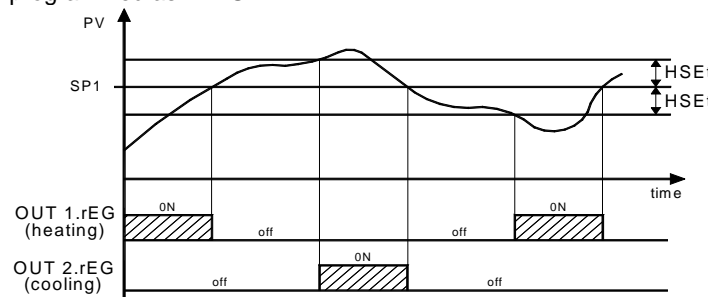
This type of control can be obtained when 2 outputs are programmed respectively as 1.rEG and 2.rEG and the par. "Cont" = nr .

The Neutral Zone control is used to control plants in which there is an element which causes a positive increase (ex. Heater, humidifier, etc.) and an element which causes a negative increase (ex. Cooler, de-humidifier, etc.).

The control functions works on the programmed outputs depending on the measurement, on the Set Point "SP1" and on the hysteresis "HSEt".

The control works in the following way: it deactivates the outputs when the process value reaches the Set Point and it activates the output 1.rEG when the process value goes below value [SP1 - HSEt], or it activates the output 2.rEG when the process value goes above [SP1 + HSEt].

Consequently, the element causing a positive increase has to be connected to the output programmed as 1.rEG while the element causing a negative increase has to be connected to the output programmed as 2.rEG.



If 2.rEG output is used to control compressor is possible to use the "Compressor Protection" function that has the meaning to avoid compressor "short cycles".

This function allows a control by time on the output 2.rEG activation, independently by the temperature control request.

The protection is a "delayed after deactivation" type.

This protection permits to avoid the output activation for a time programmable on par. "CPdt" (expressed in s); the output activation will occurs only after the elapsing of time "CPdt".

The time programmed on parameter "CPdt" is counted starting from the last output deactivation.

Obviously, whether during the time delay caused by the compressor protection function, the regulator request should stop, the output activation foreseen after time "CPdt" would be erased.

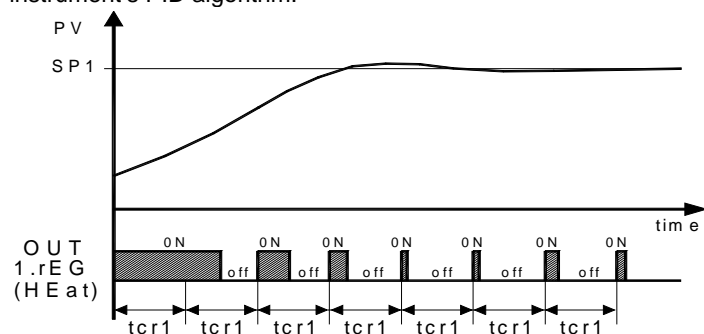
The function is not active programming "CPdt" =OFF.

The led relative to 2.rEG output blinks during the phases of output activation delay, caused by "Compressor Protection" function.

#### 4.5 - SINGLE ACTION PID CONTROL (1.rEG)

All the parameters referring to PID control are contained in the group "1.rEG".

The Single Action PID control can be obtained by programming par. "Cont" = Pid and works on the output 1.rEG depending on the Set Point "SP1", on the functioning mode "Func" and on the instrument's PID algorithm.



In order to obtain good stability of the process variable, in the event of fast processes, the cycle time "tcr1" has to have a low value with a very frequent intervention of the control output.

In this case use of a solid state relay (SSR) is recommended for driving the actuator.

The Single Action PID control algorithm foresees the setting of the following parameters :

"Pb" - Proportional Band

"tcr1" - Cycle time of the output 1.rEG

"Int" - Integral Time

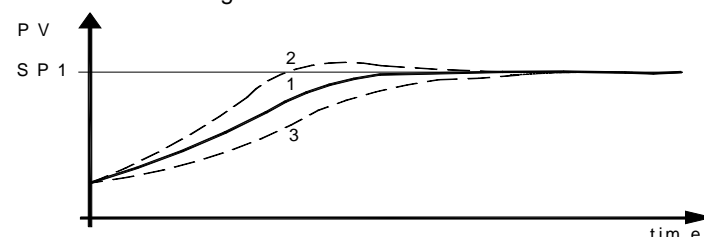
"rS" - Manual Reset (if "Int =0 only)

"dEr" - Derivative Time

"FuOC" - Fuzzy Overshoot Control

This last parameter allows the variable overshoots at the start up of the process or at the changing of the Set Point to be avoided.

Please remember that a low value on this parameter reduces the overshoot while a high value increase it.



1: Value "FuOC" OK

2: Value "FuOC" too high

3: Value "FuOC" too low

#### 4.6 - DOUBLE ACTION PID CONTROL (1.rEG - 2.rEG)

All the parameters referring to PID control are contained in the group "1.rEG".

The Double Action PID control is used to control plants where there is an element which causes a positive increase (ex. Heating) and an element which causes a negative increase (ex. Cooling).

This type of control can be obtained when 2 outputs are programmed respectively as 1.rEG and 2.rEG and the par. "Cont" = Pid.

The element causing a positive increase has to be connected to the output programmed as 1.rEG while the element causing a negative increase has to be connected to the output programmed as 2.rEG.

The Double Action PID control works on the outputs 1.rEG and 2.rEG depending on the Set Point "SP1" and on the instrument's PID algorithm.

In order to obtain good stability of the process variable, in case of fast processes, the cycle times "tcr1" and "tcr2" have to have a low value with a very frequent intervention of the control outputs.

In this case use of solid state relays (SSR) to drive the actuators is recommended.

The Double Action PID control algorithm needs the programming of the following parameters :

"Pb" - Proportional Band

"tcr1" - Cycle time of the output 1.rEG

"tcr 2" - Cycle time of the output 2.rEG

"Int" - Integral Time

"rS" - Manual Reset (if "Int =0 only)

"dEr" - Derivative Time

"FuOC" - Fuzzy Overshoot Control

"Prat" - Power Ratio or relation between power of the element controlled by output 2.rEG and power of the element controlled by output 1.rEG.

#### 4.7 - AUTOTUNING FUNCTION

All the parameters referring to the AUTOTUNING function are contained in the group "1.rEG".

The **AUTO-TUNING** function (**FAST** or **OSCILLATING** type) permits the calculation of the PID parameters by means of a tuning cycle and, at the end of this operation, the parameters are stored into the instrument's memory and remain constant during control.

Both modes calculate the following parameters automatically:

"Pb" - Proportional band

"tcr1" - output cycle time

"Int" - integral time

"dEr" - derivative time

"FuOC" - Fuzzy Overshoot Control

To activate the AUTOTUNING function, proceed as follows:

1) Set the Set point "SP1" desired.

2) Set the parameter "Cont" =Pid.

3) Program par. "Func" according to the process to be controlled through output 1.rEG.

4) Program an output as 2.rEG if the instrument controls a plant with double action

5) Set the parameter "Auto" as:

= 1 - if the autotuning is to be started automatically each time the instrument is turned on.

= 2 - if the autotuning is to be started automatically when the instrument is turned on the next time and, once tuning has been completed, the parameter "Auto"=OFF is set automatically.

= 3 - if autotuning is started up manually, by the key U

= 4 - if autotuning is to be started automatically each time the regulation set is changed.

6) Set the parameter "SEL.A" as:

= **FAST** - for FAST mode autotuning

= **OSC** - for OSCILLATING mode autotuning

*Note: the Autotuning Fast type is particularly rapid and has no effect on the control as it calculates the parameters during the Set Point reaching phase.*

*In order to correctly perform the Autotuning Fast type it's necessary that at the start of the cycle there is a certain difference between the process and the Set Point and for this reason the instrument activates the Autotuning Fast type only when :*

- For "Auto" = 1 or 2: the process value is lower (with "Func" =HEAt) than  $[SP - |SP/2|]$  or higher (with "Func" =Cool) than  $[SP + |SP/2|]$ .

- For "Auto" = 3 or 4 : the process value is lower (with "Func" =HEAt) than  $[SP - |SP/5|]$  or higher (with "Func" =Cool) than  $[SP + |SP/5|]$ .

*The Autotuning Fast type is not advisable when the Set Point is next to the initial reading or when the measured variable changes irregularly during the tuning cycle (for reasons due to the process the variable goes up or down).*

*In this cases we advice the Autotuning oscillatory type that activates some ON-OFF control cycles permitting the oscillation of the process value around the Se Point value and afterward the control swap to the PID type with those values calculated by the Autotuning.*

7) Exit the parameter programming mode.

8) Connect the instrument to the controlled system.

9) Start up autotuning turning off and on the machine if "Auto" = 1 or 2, pressing the key U if "Auto" = 3, or by varying the Set value if "Auto" = 4.

At this point, the Autotuning function is started up and is marked by the turning on of the led AT/ST.



The regulator starts up a series of operations on the connected system in order to calculate the most suitable PID regulation parameters.

If, at the FAST Auto-tuning start, the condition for the lower or higher process value is not found the display will show "ErAt" and the instrument will be swapped to normal control conditions according to the previously programmed parameters.

To make the error "ErAt" disappear, press key P.

The autotuning cycle is limited to a maximum of 12 hours.

If the process has not ended in 12 hours the instrument will show "noAt".

Instead, if a probe error should occur, the instrument will interrupt the cycle being carried out.

The values calculated by Autotuning will be memorized automatically by the instrument at the end of the correct completion of the autotuning cycle in the parameters related to PID regulation.

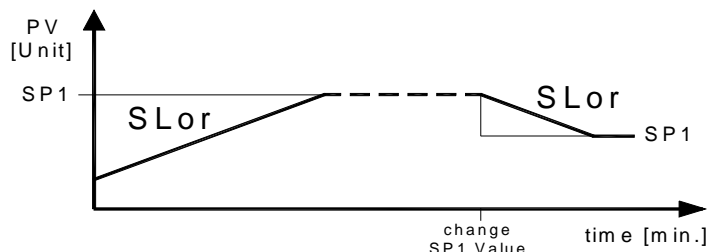
#### 4.8 - REACHING OF THE SET POINT AT CONTROLLED SPEED

All the parameters referring to the ramps functioning are contained in the group "rEG".

It is possible to reach the set point in a predetermined time (in any case longer than the time the plant would naturally need). This could be useful in those processes (heating or chemical treatments, etc.) where the set point has to be reached gradually, in a predetermined time.

The function is determined by the following parameter:

"SLor" - Gradient of ramp expressed in unit/minute



Example with start from values lower than SP 1 and with decreasing of SP 1.

**P.A.:** In case of PID control, if Auto-tuning is desired whilst the ramp function is active, this will not be carried out until the tuning cycle has been completed.

It is therefore recommended that Auto-tuning be started avoiding activating the ramp function and, once the tuning is finished, deactivate Auto-tuning ("Auto" = OFF) and program the desired ramp.

#### 4.9 - ALARM OUTPUT FUNCTIONS (AL1)

The AL1 alarm depending on the process value and before to set his functioning it's necessary to establish to which output the alarm has to correspond to.

First of all it's necessary to configure, in the parameters group "Out", the parameters relative to the outputs required as alarm ("O1F", "O2F") programming the parameter relative to the desired output as follows :

= **ALno** if the alarm output has to be ON when the alarm is active, while it's OFF when the alarm is not active

= **ALnc** if the alarm output has to be ON when the alarm is not active, while it's OFF when the alarm is active

= **ALni** if the alarm output has to be ON when the alarm is not active, while it is OFF when the alarm is active but with reverse led indication (led ON= alarm OFF).

Have now access at the group "AL1", and program on par. "OAL1", to which output the alarm signal has to be sent.

The alarm functioning is instead defined by parameters :

"AL1t" - ALARM TYPE

"AL1" - ALARM THRESHOLD

"AL1L" - LOW ALARM THRESHOLD (for band alarm) OR MINIMUM SET OF AL1 ALARM THRESHOLD (for low or high alarm)

"AL1H" - HIGH ALARM THRESHOLD (for band alarm) OR MAXIMUM SET OF AL1 ALARM THRESHOLD (for low or high alarm)

"HAL1" - ALARM HYSTERESIS

"AL1d" - ALARM ACTIVATION DELAY (in s)

"AL1i" - ALARM BEHAVIOUR IN THE EVENT OF MEASUREMENT ERROR

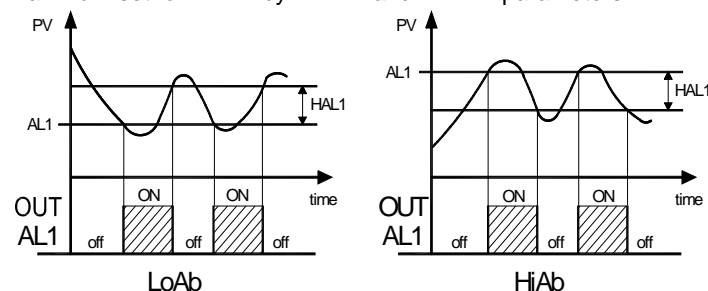
"AL1t" - ALARM TYPE: the alarm output can behave in six different ways.

**LoAb** = ABSOLUTE LOW ALARM: The alarm is activated when the process value goes below the alarm threshold set on parameter "AL1" and will be deactivated when it goes above the value [AL1+HAL1].

With this mode is possible to program the minimum and the maximum set of "AL1" by "AL1L" and "AL1H" parameters.

**HiAb** = ABSOLUTE HIGH ALARM: The alarm is activated when the process value goes higher than the alarm threshold set on parameter "AL1" and will be deactivated when it goes below the value [AL1 - HAL1].

With this mode is possible to program the minimum and the maximum set of "AL1" by "AL1L" and "AL1H" parameters.

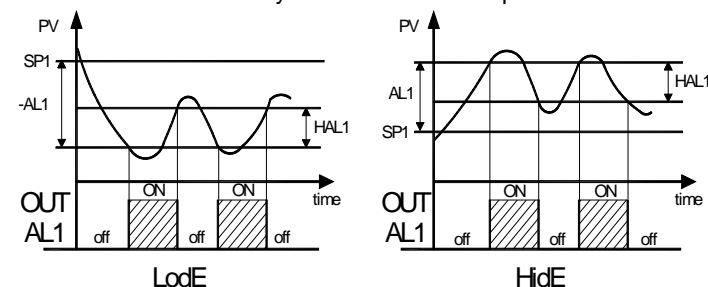


**LodE** = DEVIATION LOW ALARM: The alarm is activated when the process value goes below the value [SP1 + AL1] and will be deactivated when it goes above the value [SP1 + AL1 + HAL1].

With this mode is possible to program the minimum and the maximum set of "AL1" by "AL1L" and "AL1H" parameters.

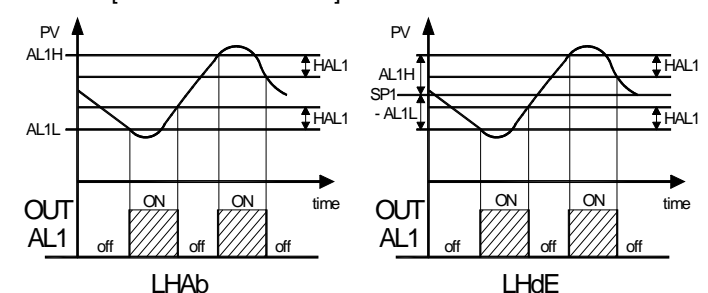
**HidE** = DEVIATION HIGH ALARM: The alarm is activated when the process value goes above the value [SP1 + AL1] and will be deactivated when it goes below the value [SP1 + AL1 - HAL1].

With this mode is possible to program the minimum and the maximum set of "AL1" by "AL1L" and "AL1H" parameters.



**LHAb** = ABSOLUTE BAND ALARM: The alarm is activated when the process value goes under the alarm threshold set on parameter "AL1L" or goes higher than the alarm threshold set on parameter "AL1H" and will be deactivated when it goes below the value [AL1H - HAL1] or when it goes above the value [AL1L + HAL1].

**LHdE** = DEVIATION BAND ALARM: The alarm is activated when the process value goes below the value [SP1 + AL1L] or goes above than the value [SP1 + AL1H] and will be deactivated when it goes below the value [SP1 + AL1H - HAL1] or when it goes above the value [SP1 + AL1L + HAL1].



**"AL1i" - ALARM ACTIVATION IN CASE OF MEASUREMENT ERROR:** This allows one to establish how the alarm have behave in the event of a measurement error (yES=alarm active; no=alarm deactivated).

### Group "1AL1" (parameters relative to alarm AL1)

Par.	Description	Range	Def.	Note
15	<b>OAL1</b> Output where alarm AL1 is addressed	Out1 / Out2 / OFF	Out2	
16	<b>AL1t</b> Alarm AL1 type: LoAb= Absolute Low HiAb= Absolute High LHAb= Absolute Band LodE= Deviation Low HidE= Deviation High LHdE= Deviation Band	LoAb / HiAb LHAb / LodE HidE / LHdE	LoAb	
17	<b>AL1</b> Alarm AL1 threshold	AL1L ÷ AL1H	0	
18	<b>AL1L</b> Low threshold band alarm AL1 or Minimum set alarm AL1 for high or low alarm	-1999 ÷ AL1H	-1999	
19	<b>AL1H</b> High threshold band alarm AL1 or Maximum set alarm AL1 for high or low alarm	AL1L ÷ 9999	9999	
20	<b>HAL1</b> Alarm AL1 hysteresis	OFF ÷ 9999	1	
21	<b>AL1d</b> Activation delay of alarm AL1	OFF ÷ 9999 sec.	OFF	
22	<b>AL1i</b> Alarm AL1 activation in case of measuring error	no / yES	no	

### Group "1rEG" (parameters relative to the control)

Par.	Description	Range	Def.	Note
23	<b>Cont</b> Control type: Pid= PID On.FA= ON/OFF asym. On.FS= ON/OFF sym. nr= ON/OFF Neutral Zone	Pid / On.FA On.FS / nr	Pid	
24	<b>Func</b> Functioning mode output 1.rEG	HEAt / Cool	HEAt	
25	<b>HSEt</b> Hysteresis of ON/OFF control	0 ÷ 9999	1	
26	<b>CPdt</b> Compressor Protection time for 2.rEG	OFF ÷ 9999 sec.	0	
27	<b>Auto</b> Autotuning Fast enable OFF = Not active 1 = Start each power on 2= Start at first power on 3= Start manually 4= Start at change Set	OFF / 1 / 2 / 3 / 4	OFF	
28	<b>SEL.A</b> Autotuning mode: FASt = FAST OSC = Oscillating	FASt / OSC	FASt	
29	<b>Pb</b> Proportional band	0 ÷ 9999	40	
30	<b>Int</b> Integral time	OFF ÷ 9999 sec.	300	
31	<b>dEr</b> Derivative time	OFF ÷ 9999 sec.	30	
32	<b>FuOc</b> Fuzzy overshoot control	0.00 ÷ 2.00	0.50	
33	<b>tcr1</b> Cycle time of output 1.rEG	0.1 ÷ 130.0 s	20.0	
34	<b>Prat</b> Power ratio 2.rEG/1.rEG	0.01 ÷ 99.99	1.00	
35	<b>tcr2</b> Cycle time of 2.rEG	0.1 ÷ 130.0 s	10.0	
36	<b>rS</b> Manual reset	-100.0 ÷ 100.0 %	0.0	
37	<b>SLor</b> Gradient of ramp: InF= Ramp not active	0.00 ÷ 99.99 / InF unit/min.	InF	

### Group "1PAn" (parameters relative to the user interface)

Par.	Description	Range	Def.	Note
38	<b>AdE</b> Shift value for the shift index functioning	OFF... 9999	2	

## 6 - PROBLEMS, MAINTENANCE AND GUARANTEE

### 6.1 - ERROR SIGNALLING

Error	Reason	Action
---	Probe interrupted	Verify the correct connection between probe and instrument and then verify the correct functioning of the probe
uuuu	The measured variable is under the probe's limits (under-range)	
oooo	The measured variable is over the probe's limits (over-range)	
ErAt	Auto-tuning not possible	Push key "P" in order to make the error message disappear. Once the error has been found, try to repeat the auto-tuning.
noAt	Auto-tuning not finished within 12 hours	Check the functioning of probe and actuator and try to repeat the auto-tuning.
ErEP	Possible anomaly of the EEPROM memory	Push key "P"

In error conditions, the instrument provides an output power as programmed on par "OPE" and activates the alarm, if the relative parameter "AL1i" have been programmed = yES.

### 6.2 - CLEANING

We recommend cleaning of the instrument with a slightly wet cloth using water and not abrasive cleaners or solvents which may damage the instrument.

### 6.3 - WARRANTY AND REPAIRS

The instrument is under warranty against manufacturing flaws or faulty material, that are found within 18 months from delivery date. The warranty is limited to repairs or to the replacement of the instrument. The eventual opening of the housing, the violation of the instrument or the improper use and installation of the product will bring about the immediate withdrawal of the warranty's effects.

In the event of a faulty instrument, either within the period of warranty, or further to its expiry, please contact our sales department to obtain authorisation for sending the instrument to our company. The faulty product must be shipped to Ascon Tecnologic with a detailed description of the faults found, without any fees or charge for Ascon Tecnologic, except in the event of alternative agreements.

## 7 - TECHNICAL DATA

### 7.1 - ELECTRICAL DATA

Power supply: 24 VAC/VDC, 100... 240 VAC ±10%

Frequency AC: 50/60 Hz

Power consumption: 4 VA approx.

Input/s: 1 input for temperature probes: tc J, K, S; infrared sensors Ascon Tecnologic ZIS J e K; RTD Pt 100 IEC; PTC KTY 81-121 (990 Ω @ 25°C); NTC 103AT-2 (10kΩ @ 25°C) or mV signals 0... 50 mV, 0... 60 mV, 12... 60 mV or normalized signals 0/4... 20 mA, 0... 1 V, 0/1... 5 V, 0/2... 10 V.

Normalized signals input impedance: 0/4... 20 mA: 51 Ω; mV and V: 1 MΩ

Output/s: Up to 2 outputs. Relay OUT1: SPDT, OUT2: SPST-NO (8A-AC1, 3A-AC3 250 VAC, 1/2HP 250VAC, 1/3HP 125 VAC); or in tension to drive SSR (8mA/ 8VDC).

Auxiliary supply output: 12 VDC / 20 mA Max.

Electrical life for relay outputs: 100000 operat.

Installation category: II

Measurement category: I

Protection class against electric shock: Class II for Front panel

Insulation: Reinforced insulation between the low voltage part (power supply and relay outputs) and front panel; Reinforced insulation between the low voltage section (Supply and relay outputs) and the extra low voltage section (input, SSR outputs);



Reinforced between power supply and relays; No insulation between input and SSR outputs.

7.2 - MECHANICAL DATA

Housing: Self-extinguishing plastic, UL 94 V0

Dimensions: 72 x 72 mm DIN, depth 97 mm

Weight: 215 g approx.

Mounting: Flush in panel in 67 x 67 mm hole

Connections: extractable 2.5 mm<sup>2</sup> screw terminal block

Degree of protection of front panel: IP 54 mounted in panel with gasket

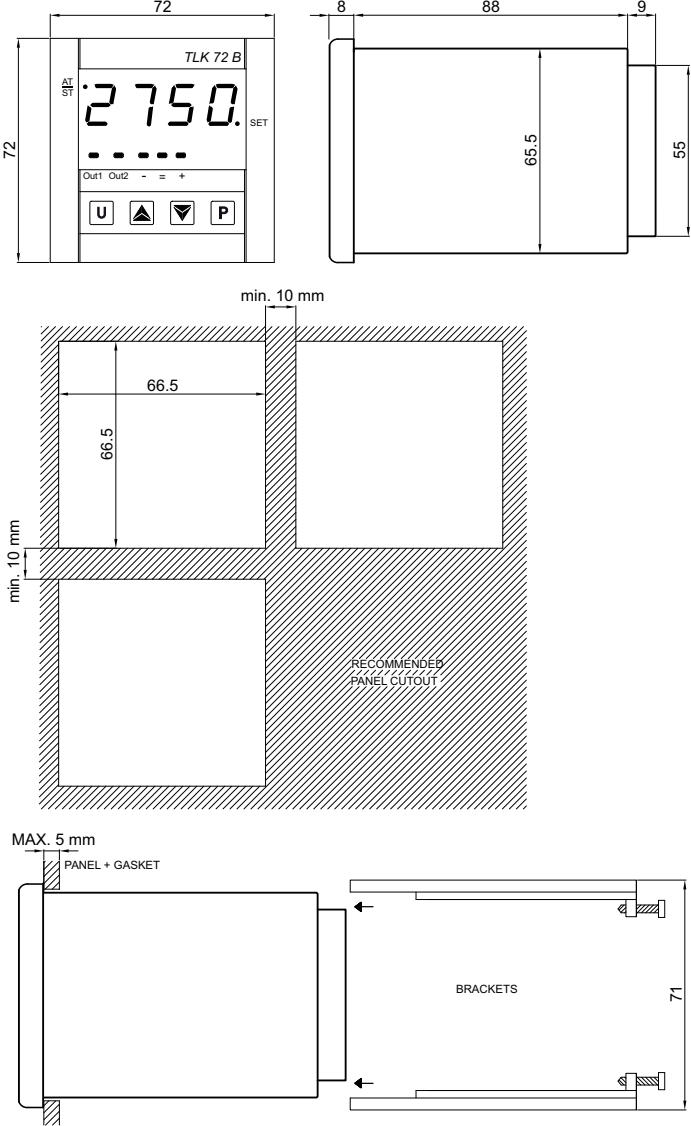
Pollution situation: Normal

Operating temperature: 0... 50°C

Operating humidity: 30... 95 RH% without condensation

Storage temperature: -10... +60°C

7.3 - DIMENSIONS, PANEL CUT-OUT AND MOUNTING [mm]



7.4 - FUNCTIONAL FEATURES

Control: ON/OFF, ON/OFF Neutral Zone, PID single Action, PID double action.

Measurement range: according to the used probe (see range table)

Display resolution: according to the probe used 1/0,1/0,01/0,001

Overall accuracy:  $\pm(0,5 \% fs + 1 \text{ digit})$  ; tc S:  $\pm(1 \% fs + 1 \text{ digit})$

Max cold junction compensation drift (in tc): 0,1°C/°C with operating temperature 0... 50°C after warm-up of 20 min.

Sampling rate: 130 ms.

Display: 4 Digit Red h 14 mm

Compliance: ECC directive EMC 2004/108/CE (EN 61326), ECC directive LV 2006/95/CE (EN 61010-1)

Approvals: C-UL (file n. E206847)

7.5 - MEASURING RANGE TABLE

INPUT	"dP" = 0	"dP" = 1, 2, 3
tc J "SEnS" = J	0... 1000°C 32... 1832°F	- - - -
tc K "SEnS" = CrAl	0... 1370°C 32... 2498°F	- - - -
tc S "SEnS" = S	0... 1760°C 32... 3200°F	- - - -
Pt100 (IEC) "SEnS" = Pt1	-200... 850°C -328... 1562°F	-199.9... 850.0°C -199.9... 999.9°F
PTC (KTY81-121) "SEnS" = Ptc	-55... 150°C -67... 302°F	-55.0... 150.0°C -67.0... 302.0°F
NTC (103-AT2) "SEnS" = ntc	-50... 110°C -58... 230°F	-50.0... 110.0°C -58.0... 230.0°F
0... 20 mA "SEnS" = 0.20	-1999... 9999	-199.9... 999.9
4... 20 mA "SEnS" = 4.20		
0... 50 mV "SEnS" = 0.50		
0... 60 mV "SEnS" = 0.60		
12... 60 mV "SEnS" = 12.60		
0... 1 V "SEnS" = 0.1		
0... 5 V "SEnS" = 0.5		
1... 5 V "SEnS" = 1.5		
0... 10 V "SEnS" = 0.10		
2... 10 V "SEnS" = 2.10		

7.6 - INSTRUMENT ORDERING CODE

TLK72 a b c d e f g hh B

a: POWER SUPPLY

L = 24 VAC/VDC

H = 100... 240 VAC

b: INPUT

C = thermocouples (J, K, S, I.R.), mV, thermoresistances (Pt100)

E = thermocouples (J, K, S, I.R.), mV, thermistors (PTC, NTC)

I = normalized signals 0/4... 20 mA

V = normalized signals 0... 1 V, 0/1... 5 V, 0/2... 10 V.

c: OUTPUT OUT1

R = Relay

O = VDC for SSR

d: OUTPUT OUT2

R = Relay

O = VDC for SSR

- = None

e: UNAVAILABLE CODES

f: UNAVAILABLE CODES

g: UNAVAILABLE CODES

hh: SPECIAL CODES

TLK 72 B PASSWORD = 381