# **₩TLK 48 B**

# MICROPROCESSOR-BASED DIGITAL **ELECTRONIC CONTROLLER**



# **OPERATING INSTRUCTIONS** Vr. 03 (ENG) - 12/04 - cod.: ISTR 06877

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## FOREWORD



for the product to be installed correctly and also Thermoresistances PT100. is paid to the following instructions and to save Thermistors PTC and NTC.

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## 1 - INSTRUMENT DESCRIPTION

### **1.1 - GENERAL DESCRIPTION**

TLK 48 B is a digital microprocessor-based controller, with ON/OFF, Neutral Zone ON/OFF, PID single action, PID dual action (direct and reverse) control and with AUTOTUNING function (FAST or OSCILLATING type).

The process value is visualized on 4 red displays, while the output status is indicated by 2 LED displays.

The instrument is equipped with a 3 LED programmable shift indexes and can have up to 2 outputs: relay type or can drive solid state relays type (SSR).

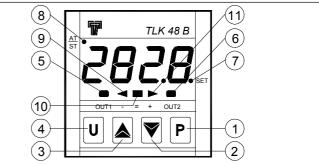
Depending on the model required the input accept:

C: Thermocouples temperature probes (J,K,S and TECNOLOGIC This manual contains the information necessary IRS Infrared sensors), mV signals (0..50/60 mV, 12..60 mV),

instructions for its maintenance and use; we E : Thermocouples temperature probes (J,K,S and TECNOLOGIC therefore recommend that the utmost attention IRS Infrared sensors), mV signals (0..50/60 mV, 12..60 mV),

- I : normalized analogue signals 0/4..20 mA

## **1.2 - FRONT PANEL DESCRIPTION**



## it.

1 - Key P : This is used to access the programming parameters and to confirm selection.

2 - Key DOWN : This is used to decrease the values to be set and to select the parameters. If the key is held down, the user returns to the previous programming level until he exits the programming mode.

3 - Key UP : This is used to increase the values to be set and to select the parameters. If the key is held down, the user returns to the previous programming level until he exits the programming mode. Outside the programming mode it permits visualisation of the output control power.

4 - Key U : It can used to Activate Autotuning function and modify "P" and the display will show "0". the visibility of the parameters in "ConF" menu (see par. 2.3).

5 - Led OUT1 : indicates the state of output OUT1

6 - Led OUT2 : indicates the state of output OUT2

7 - Led SET : It indicates access to the programming mode and programming mode. parameter programming level.

8 - Led AT/ST : indicates that the Autotuning is in progress.

9 - Led - Shift index: indicates that the process value is lower than [SP1-AdE].

10 - Led = Shift index: indicates that the process value is within the range [SP1+AdE ... SP1-AdE]

11 - Led + Shift index: indicates that the process value is higher than [SP1+AdE].

#### 2 - PROGRAMMING

#### 2.1 - FAST PROGRAMMING OF THE SET POINT

This procedure permits rapid programming of the Set Point (SP1) and the alarm threshold (AL1).

Push key "P", then release it and the display will visualise "SP 1" alternatively to the programmed value.

To modify the value, press "UP" key to increase it or the "DOWN" key to decrease it.

These keys change the value one digit at a time but if they are Release the key and by using the "UP" and "DOWN" keys, it will be pressed for more than one second, the value increases or decreases rapidly and, after two seconds in the same condition, the To exit the programming mode, no key should be pressed for changing speed increases in order to allow the desired value to be reached rapidly.

Once the desired value has been reached, by pushing key P it is The programming and exit modes for the "OPEr" menu are the possible to exit by the fast programming mode, or (if the instrument same as those described for menu "ConF" with the difference that have an output configured as alarm) it is possible to visualise and to access the menù "OPEr" the Password is not required. modify the "AL1" alarm threshold like Set "SP1".

To exit the fast Set programming it is necessary to push key P, after the visualisation of the last Set Point, or alternatively, if no key is pressed for approx. 15 seconds, the display will return to normal functioning automatically.

Set Point "SP1" can be programmed with a value that is between the value programmed on par. "SPLL" and the one programmed on par. "SPHL".

#### 2.2 - PARAMETERS PROGRAMMING

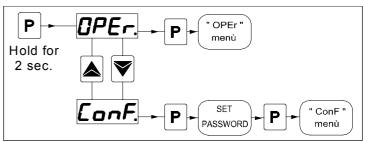
By pushing key "P" and holding it down for approx. 2 sec. it is possible to enter into the main selection menu.

Using the "UP" or DOWN" keys, it is then possible to roll over the 2.3 - PARAMETERS PROGRAMMING LEVELS selections:

"OPEr"	to enter into the operating parameters menu	
"ConF"	to enter into the configuration parameters menu	
	(PASSWORD is required)	

Once the desired item has been selected, push key "P" to confirm. Selecting "OPEr" and "ConF" gives the possibility of accessing other menus containing additional parameters and more precisely : "OPEr" - Operating parameters Menu: this normally contains the menu "ConF", if instead the LED is on, this means that the Set Point "SP1" and the alarm threshold "AL1" parameters but it parameter is also programmable in the menu "OPEr". can contain all the desired parameters (see par. 2.3).

operating parameters and the functioning configuration parameters. ATTENTION: The instrument is programmed in factory with all the The Set Point "SP1" and the alarm threshold "AL1" will only be parameters, to exception of the Set Point "SP1" and the alarm visible on the Set Point fast programming level (described in par. threshold "AL1", programmable in the menù "ConF" to the purpose 2.1) if are present in the menu "OPEr"). to prevent wrong accidental programming from non experienced consumers.



To enter the menu "ConF" select the option "ConF", press the key

At this request, enter, using keys "UP" and "DOWN", the number reported on the last page of this manual and push key "P".

If an incorrect password is entered, the instrument exit from

If the password is correct, the display will visualise the code identifying the first group of parameters (" 1SP ") and with keys "UP" and "DOWN" it will be possible to select the desired group of parameters.

Once the desired group of parameters has been selected, the code identifying the first parameter of the selected group will be visualised by pushing the "P" key. Again using the "UP" and "DOWN" keys, it is possible to select the

desired parameter and, if the key "P" is pressed, the display will alternatively show the parameter's code and its programming value, which can be modified by using the "UP" or "DOWN" keys.

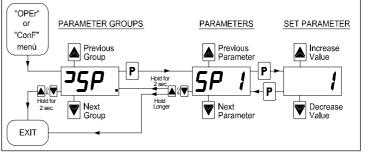
Once the desired value has been programmed, push key "P" once more: the new value will be memorised and the display will show only the code of the selected parameter.

By using the "UP" or "DOWN" keys, it is then possible to select a new parameter (if present) and modify it as described above.

To select another group of parameters, keep the "UP" or "DOWN" key pressed for approx. 2 sec., afterwards the display will return to visualise the code of the group of parameters.

possible to select a new group.

approx. 20 seconds, or keep the "UP" or "DOWN" pressed until exit from the programming mode is obtained.



The menu "OPEr" normally contains the parameter "SP1"; however it is possible to make all desired parameters appear or disappear on this level, by following this procedure:

Enter the menu "ConF" and select the parameter to be made programmable or not programmable in the menu "OPEr".

Once the parameter has been selected, if the LED SET is switched off, this means that the parameter is programmable only in the

To modify the visibility of the parameter, push key "U" : the LED "ConF" - Configuration parameters Menu: this contains all the SET will change its state indicating the parameter accessibility level (on = menu "OPEr" and "ConF"; off = menu "ConF" only).

#### **3 - INFORMATION ON INSTALLATION AND USE**

#### 3.1 - PERMITTED USE

The instrument has been projected and manufactured as a measuring and control device to be used according to EN61010-1 for the altitudes operation until 2000 ms.

The use of the instrument for applications not expressly permitted by the above mentioned rule must adopt all the necessary protective measures.

The instrument CANNOT be used in dangerous environments (flammable or explosive) without adequate protection.

The installer must ensure that EMC rules are respected, also after the instrument installation, if necessary using proper filters.

Whenever a failure or a malfunction of the device may cause dangerous situations for persons, thing or animals, please remember that the plant has to be equipped with additional devices which will guarantee safety.

#### **3.2 – MECHANICAL MOUNTING**

The instrument, in DIN case 48 x 48 mm, is designed for flush-in panel mounting.

Make a hole 45 x 45 mm and insert the instrument, fixing it with the provided special bracket.

We recommend that the gasket is mounted in order to obtain the front protection degree as declared. Avoid placing the instrument in

environments with very high humidity levels or dirt that may create 4.1 - MEASURING AND VISUALIZATION condensation or introduction of conductive substances into the All the parameters referring measurements are contained in the instrument.

Ensure adequate ventilation to the instrument and avoid installation Depending on the model required the input accept: in containers that house devices which may overheat or which may C: Thermocouples temperature probes (J,K,S and TECNOLOGIC cause the instrument to function at a higher temperature than the IRS Infrared sensors), mV signals (0..50/60 mV, 12..60 mV), one permitted and declared.

electromagnetic disturbances such as motors, power relays, relays, solenoid valves, etc.

The instrument can be removed from its housing from the front side I: normalized analogue signals 0/4..20 mA : it is recommended that the instrument be disconnected from the V: normalized analogue signals 0..1 V, 0/1..5 V, 0/2..10 V power supply when it is necessary to carry out this operation.

#### **3.3 - ELECTRICAL CONNECTION**

terminal, according to the following diagram, checking that the - for thermoresistances Pt100 IEC (Pt1) or thermistors PTC power supply is the same as that indicated on the instrument and KTY81-121 (Ptc) or NTC 103AT-2 (ntc) that the load current absorption is no higher than the maximum - for normalised signals in current 0..20 mA (0.20) or 4..20 mA electricity current permitted.

As the instrument is built-in equipment with permanent connection - for normalised signals in tension 0..1 V (0.1), 0..5 V (0.5), 1..5 V inside housing, it is not equipped with either switches or internal (1.5), 0..10 V (0.10) or 2..10 V (2.10). devices to protect against overload of current: the installation will - for normalised signals in tension 0..50 mV (0.50), 0..60 mV (0.60), include an overload protection and a two-phase circuit-breaker, 12..60 mV (12.60). placed as near as possible to the instrument, and located in a We recommend to switch on and off the instrument when these position that can easily be reached by the user and marked as parameters are modified, in order to obtain a correct measuring. instrument disconnecting device which interrupts the power supply For the instruments with input for temperature probes (tc, rtd) it's to the equipment.

connected to the instrument must be protect properly, using desired resolution (0=1°; 1=0,1°). devices (ex. fuses) proportionate to the circulating currents.

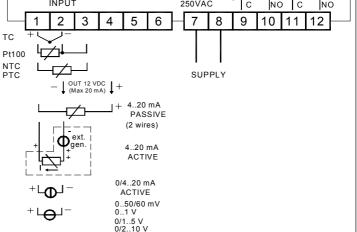
according to the working voltages and temperatures, be used.

Furthermore, the input cable of the probe has to be kept separate from line voltage wiring. If the input cable of the probe is screened, beginning of the scale (0/4 mA, 0/12 mV, 0/1 V o 0/2 V) and, on it has to be connected to the ground with only one side.

We recommend that a check should be made that the parameters of the scale (20 mA, 50 mV, 60 mV, 5 V or 10 V). are those desired and that the application functions correctly before connecting the outputs to the actuators so as to avoid used to recalibrate the instrument according to application needs, malfunctioning that may cause irregularities in the plant that could by using par. "OFSt" and "rot". cause damage to people, things or animals.

#### **TLK48 B** RELAYS: 8A-AC1 (3A-AC3) 250VAC INPUT 2 4 5 6 8 1 3 7 9 10 11

3.4 - ELECTRICAL WIRING DIAGRAM



OUT2

OUT1

#### **4 - FUNCTIONS**

aroup "InP".

Thermoresistances PT100.

Connect the instrument as far away as possible from sources of E : Thermocouples temperature probes (J,K,S and TECNOLOGIC IRS Infrared sensors), mV signals (0..50/60 mV, 12..60 mV), Thermistors PTC and NTC.

Depending on the model, using par. "SEnS", it's possible to select the type of input probe, which can be :

- for thermocouples J (J), K (CrAL), S (S) or for infrared sensors Carry out the electrical wiring by connecting only one wire to each serie TECNOLOGIC IRTC1 with linearization J (Ir.J) or K (Ir.CA)

(4.20)

possible to select, through par. "Unit", the unit of measurement

It is also recommended that the supply of all the electrical circuits (°C, °F) and, through par. "dP" (Pt100, PTC and NTC only) the

Instead, with regards to the instruments with normalised analogue It is strongly recommended that cables with proper insulation, input signals, it is first necessary to program the desired resolution on par. "dP" (0=1; 1=0,1; 2=0,01; 3=0,001) and then, on par. "SSC", the value that the instrument must visualise at the par. "FSC", the value that the instrument must visualise at the end

The instrument allows for measuring calibration, which may be

Programming par. "rot"=1,000, in par. "OFSt" it is possible to set a positive or negative offset that is simply added to the value read by the probe before visualisation, which remains constant for all the measurements.

If instead, it is desired that the offset set should not be constant for all the measurements, it is possible to operate the calibration on any two points.

"OFSt" and "rot", the following formulae must be applied :

"rot" = (D2-D1) / (M2-M1) "OFSt" = D2 - ("rot" x M2) where:

M1 =measured value 1

D1 = visualisation value when the instrument measures M1 M2 =measured value 2

D2 = visualisation value when the instrument measures M2 It then follows that the instrument will visualise :

DV = MV x "rot" + "OFSt"

where: DV = visualised value MV= measured value

Example 1: It is desired that the instrument visualises the value effectively measured at 20° but that, at 200°, it visualises a value lower than 10° (190°).

Therefore : M1=20 ; D1=20 ; M2=200 ; D2=190 "rot" = (190 - 20) / (200 - 20) = 0,944

"OFSt" = 190 - (0,944 x 200) = 1,2

Example 2: It is desired that the instrument visualises 10° whilst the value actually measured is 0°, but, at 500° it visualises a 50° higher value (550°).

Therefore : M1=0 ; D1=10 ; M2=500 ; D2=550 "rot" = (550 - 10) / (500 - 0) = 1,08 "OFSt" = 550 - (1,08 x 500) = 10

By using par. "FiL" it is possible to program time constant of the software filter for the input value measured, in order to reduce noise sensitivity (increasing the time of reading).

In case of measurement error, the instrument supplies the power as programmed on par. "OPE".

for the PID controller, while for the ON/OFF controllers the cycle an element which causes a positive increase (ex. Heater, time is automatically considered to be equal to 20 sec. (e.g. In the humidifier, etc.) and an element which causes a negative increase event of probe error with ON/OFF control and "OPE"=50, the (ex. Cooler, de-humidifier, etc). control output will be activated for 10 sec., then it will be The control functions works on the programmed outputs depending deactivated for 10 sec. and so on until the measurement error on the measurement, on the Set Point "SP1" and on the hysteresis remains.).

In the group "PAn" the par. "AdE" is present that defines the 3 led shift index functioning.

The lighting up of the green led = indicates that the process value is within the range [SP1+AdE ... SP1-AdE], the lighting up of the HSEt], or it activates the output 2.rEG when the process value goes led - indicates that the process value is lower than [SP1-AdE] and above [SP1 + HSEt]. the lighting up of the led + indicates that the process value is higher Consequently, the element causing a positive increase has to be than [SP1+AdE].

#### **4.2 - OUTPUTS CONFIGURATION**

The instrument's outputs can be programmed by entering the group of parameters "'Out, where the relative parameters "O1F" and "O2F" (depending on the number of outputs available on the instrument) are located.

- The outputs can be set for the following functions :
- Main control output (1.rEG)
- Secondary control output (2.rEG)
- Alarm output normally open (ALno)
- Alarm output normally closed (ALnc)
- Alarm output normally closed with led reverse indication (ALni) - Output deactivated (OFF)

made in the group referring to the alarm to the alarm ("IAL1").

#### 4.3 - ON/OFF CONTROL (1.rEG)

All the parameters referring to the ON/OFF control are contained in the group "'rEG".

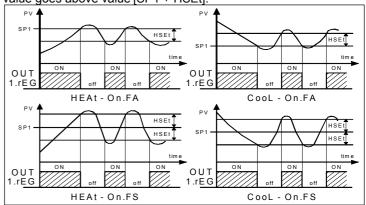
On.FS or = On.FA and works on the output programmed as **1.rEG**, programmable on par. "CPdt" (expressed in sec.); the output This type of control can be obtained by programming par."Cont" = depending on the measure, on the Set Point "SP1", on the functioning mode "Func" and on the hysteresis "HSEt"

The instrument carries out an ON/OFF control with symmetric hysteresis if "Cont" = On.FS or with asymmetrical hysteresis if "Cont" = On.FA.

The control works in the following way : in the case of reverse action, or heating ("FunC"=HEAt), it deactivates the output, when The led relative to 2.rEG output blinks during the phases of output the process value reaches [SP1 + HSEt] in case of symmetrical

In this case, in order to decide which values to program on par. hysteresis, or [SP1] in case of asymmetrical hysteresis and is then activated again when the process value goes below value [SP1 -HSEt].

Vice versa, in case of direct action or cooling ("Func"=CooL), it deactivates the output, when the process value reaches [SP1 -HSEt] in case of symmetrical hysteresis, or [SP1] in case of asymmetrical hysteresis and is activated again when the process value goes above value [SP1 + HSEt].



#### 4.4 - NEUTRAL ZONE ON/OFF CONTROL (1.rEG - 2.rEG)

All the parameters referring to Neutral Zone ON/OFF control are contained in the group "IrEG".

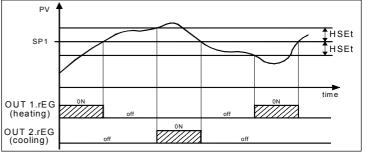
This type of control can be obtained when 2 outputs are programmed respectively as 1.rEG and 2.rEG and the par. "Cont" = nr .

This power will be calculated according to cycle time programmed The Neutral Zone control is used to control plants in which there is

"HSEt".

The control works in the following way : it deactivates the outputs when the process value reaches the Set Point and it activates the output 1.rEG when the process value goes below value [SP1 -

connected to the output programmed as 1.rEG while the element causing a negative increase has to be connected to the output programmed as 2.rEG.



The coupling outputs number outputs - number alarms can be If 2.rEG output is used to control compressor is possible to use the "Compressor Protection" function that has the meaning to avoid compressor "short cycles".

This function allows a control by time on the output 2.rEG activation, independently by the temperature control request.

The protection is a "delayed after deactivation" type.

This protection permits to avoid the output activation for a time activation will occurs only after the elapsing of time "CPdt".

The time programmed on parameter "CPdt" is counted starting from the last output deactivation.

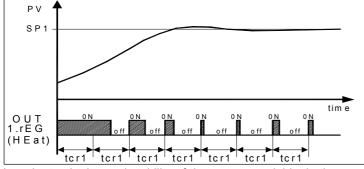
Obviously, whether during the time delay caused by the compressor protection function, the regulator request should stop, the output activation foreseen after time "CPdt" would be erased.

The function is not active programming "CPdt" = OFF. activation delay, caused by "Compressor Protection" function.

#### 4.5 - SINGLE ACTION PID CONTROL (1.rEG)

All the parameters referring to PID control are contained in the "Int" - Integral Time group "'rEG".

The Single Action PID control can be obtained by programming "dEr" - Derivative Time par."Cont" = Pid and works on the output 1.rEG depending on the "FuOC" - Fuzzy Overshoot Control Set Point "SP1", on the functioning mode "Func" and on the "Prat" - Power Ratio or relation between power of the element instrument's PID algorithm.



In order to obtain good stability of the process variable, in the event "Int" - integral time of fast processes, the cycle time "tcr1" has to have a low value with "dEr" - derivative time a very frequent intervention of the control output.

In this case use of a solid state relay (SSR) is recommended for driving the actuator.

The Single Action PID control algorithm foresees the setting of the following parameters :

"Pb" - Proportional Band

"tcr1" - Cycle time of the output 1.rEG

"Int" - Integral Time

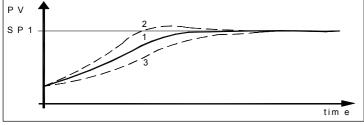
"rS" - Manual Reset (if "Int =0 only)

"dEr" - Derivative Time

"FuOC" - Fuzzy Overshoot Control

This last parameter allows the variable overshoots at the start up of = 2 - if the autotuning is to be started automatically when the the process or at the changing of the Set Point to be avoided.

Please remember that a low value on this parameter reduces the overshoot while a high value increase it.



1: Value "FuOC" OK

2: Value "FuOC" too high

3: Value "FuOC" too low

#### 4.6 - DOUBLE ACTION PID CONTROL (1.rEG - 2.rEG)

All the parameters referring to PID control are contained in the group "'rEG".

The Double Action PID control is used to control plants where there is an element which causes a positive increase (ex. Heating) and an element which causes a negative increase (ex. Cooling).

This type of control can be obtained when 2 outputs are programmed respectively as 1.rEG and 2.rEG and the par. "Cont" = Pid.

The element causing a positive increase has to be connected to the output programmed as 1.rEG while the element causing a negative the process value around the Se Point value and afterward the increase has to be connected to the output programmed as 2.rEG.

The Double Action PID control works on the outputs 1.rEG and Autotuning. 2.rEG depending on the Set Point "SP1" and on the instrument's PID algorithm.

In order to obtain good stability of the process variable, in case of 9) Start up autotuning turning off and on the machine if "Auto" = 1 fast processes, the cycle times "tcr1" and "tcr2" have to have a low or 2, pressing the key U if "Auto" = 3, or by varying the Set value if value with a very frequent intervention of the control outputs.

In this case use of solid state relays (SSR) to drive the actuators is At this point, the Autotuning function is started up and is marked by recommended.

The Double Action PID control algorithm needs the programming of The regulator starts up a series of operations on the connected the following parameters :

"Pb" - Proportional Band

"tcr1" - Cycle time of the output 1.rEG

"tcr 2" - Cycle time of the output 2.rEG

"rS" - Manual Reset (if "Int =0 only)

controlled by output 2.rEG and power of the element controlled by output 1.rEG.

#### 4.7 - AUTOTUNING FUNCTION

All the parameters referring to the AUTOTUNING function are contained in the group "IrEG".

The AUTO-TUNING function (FAST or OSCILLATING type) permits the calculation of the PID parameters by means of a tuning cycle and, at the end of this operation, the parameters are stored into the instrument's memory and remain constant during control. Both modes calculate the following parameters automatically:

"Pb" - Proportional band

"tcr1" - output cycle time

"FuOC" - Fuzzy Overshoot Control

To activate the AUTOTUNING function, proceed as follows:

1) Set the Set point "SP1" desired.

2) Set the parameter "Cont" =Pid.

3) Program par. "Func" according to the process to be controlled through output 1.rEG.

4) Program an output as 2.rEG if the instrument controls a plant with double action

5) Set the parameter "Auto" as:

= 1 - if the autotuning is to be started automatically each time the instrument is turned on.

instrument is turned on the next time and, once tuning has been completed, the parameter "Auto"=OFF is set automatically.

= 3 - if autotuning is started up manually, by the key U

= 4 - if autotuning is to be started automatically each time the regulation set is changed.

6) Set the parameter "A.SEL" as:

= FASt - for FAST mode autotuning

= OSC - for OSCILLATING mode autotuning

Note : the Autotuning Fast type is particularly rapid and has no effect on the control as it calculates the parameters during the Set Point reaching phase.

In order to correctly perform the Autotuning Fast type it's necessary that at the start of the cycle there is a certain difference between the process and the Set Point and for this reason the instrument activates the Autotuning Fast type only when :

- For "Auto" = 1 or 2: the process value is lower (with "Func" =HEAt) than [SP- |SP/2|] or higher (with "Func" =CooL) than [SP+ |SP/2|].

- For "Auto" = 3 or 4 : the process value is lower (with "Func" =HEAt) than [SP- |SP/5|] or higher (with "Func" =CooL) than [SP+ |SP/5|].

The Autotuning Fast type is not advisable when the Set Point is next to the initial reading or when the measured variable changes irregularly during the tuning cycle (for reasons due to the process the variable goes up or down).

In this cases we advice the Autotuning oscillatory type that activates some ON-OFF control cycles permitting the oscillation of control swap to the PID type with those values calculated by the

7) Exit the parameter programming mode.

Connect the instrument to the controlled system.

"Auto" = 4.

the turning on of the led AT/ST.

system in order to calculate the most suitable PID regulation parameters.

If, at the FAST Auto-tuning start, the condition for the lower or "AL1i" - ALARM higher process value is not found the display will show "ErAt" and MEASUREMENT ERROR the instrument will be swapped to normal control conditions

according to the previously programmed parameters.

To make the error "ErAt" disappear, press key P.

The autotuning cycle is limited to a maximum of 12 hours.

If the process has not ended in 12 hours the instrument will show "noAt" .

Instead, if a probe error should occur, the instrument will interrupt [AL1+HAL1]. the cycle being carried out.

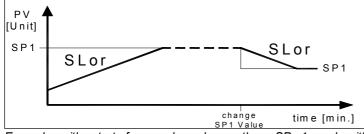
The values calculated by Autotuning will be memorized automatically by the instrument at the end of the correct completion HiAb = ABSOLUTE HIGH ALARM: The alarm is activated when the of the autotuning cycle in the parameters related to PID regulation.

#### 4.8 - REACHING OF THE SET POINT AT CONTROLLED SPEED

All the parameters referring to the ramps functioning are contained With this mode is possible to program the minimum and the in the group "'rEG".

It is possible to reach the set point in a predetermined time (in any case longer than the time the plant would naturally need). This could be useful in those processes (heating or chemical treatments, etc.) where the set point has to be reached gradually, in a predetermined time.

The function is determined by the following parameter : "SLor" - Gradient of ramp expressed in unit/minute



Example with start from values lower than SP 1 and with decreasing of SP 1.

P.A.: In case of PID control, if Auto-tuning is desired whilst the ramp function is active, this will not be carried out until the tuning cycle has been completed.

It is therefore recommended that Auto-tuning be started avoiding activating the ramp function and, once the tuning is finished, deactivate Auto-tuning ("Auto" = OFF) and program the desired ramp.

#### 4.9 - ALARM OUTPUT FUNCTIONS (AL1)

The AL1 alarm depending on the process value and before to set his functioning it's necessary to establish to which output the alarm has to correspond to.

First of all it's necessary to configure, in the parameters group "Out", the parameters relative to the outputs required as alarm ("O1F", "O2F") programming the parameter relative to the desired the process value goes under the alarm threshold set on parameter output as follows :

= ALno if the alarm output has to be ON when the alarm is active, while it's OFF when the alarm is not active

= ALnc if the alarm output has to be ON when the alarm is not LHdE = DEVIATION BAND ALARM: The alarm is activated when active, while it's OFF when the alarm is active

= ALni if the alarm output has to be ON when the alarm is not active, while it is OFF when the alarm is active but with reverse led indication (led ON= alarm OFF).

Have now access at the group "AL1", and program on par. "OAL1", to which output the alarm signal has to be sent.

The alarm functioning is instead defined by parameters :

"AL1t " – ALARM TYPE

"AL1" - ALARM THRESHOLD

"AL1L" - LOW ALARM THRESHOLD (for band alarm) OR MINIMUM SET OF AL1 ALARM THRESHOLD (for low or high alarm)

"AL1H" - HIGH ALARM THRESHOLD (for band alarm) OR MAXIMUM SET OF AL1 ALARM THRESHOLD (for low or high alarm)

"HAL1" - ALARM HYSTERESIS

"AL1d" - ALARM ACTIVATION DELAY (in sec.)

BEHAVIOUR IN THE EVENT OF

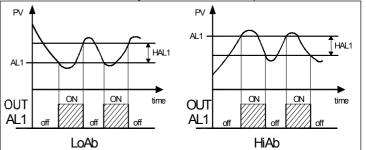
"AL1t" - ALARM TYPE : the alarm output can behave in six different ways.

LoAb = ABSOLUTE LOW ALARM: The alarm is activated when the process value goes below the alarm threshold set on parameter "AL1" and will be deactivated when it goes above the value

With this mode is possible to program the minimum and the maximum set of "AL1" by "AL1L" and "AL1H" parameters.

process value goes higher than the alarm threshold set on parameter "AL1" and will be deactivated when it goes below the value [AL1 - HAL1].

maximum set of "AL1" by "AL1L" and "AL1H" parameters.

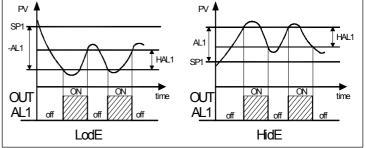


LodE = DEVIATION LOW ALARM: The alarm is activated when the process value goes below the value [SP1 + AL1] and will be deactivated when it goes above the value [SP1 + AL1 + HAL1].

With this mode is possible to program the minimum and the maximum set of "AL1" by "AL1L" and "AL1H" parameters.

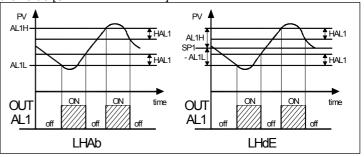
HidE = DEVIATION HIGH ALARM: The alarm is activated when the process value goes above the value [SP1 + AL1] and will be deactivated when it goes below the value [SP1 + AL1 - HAL1].

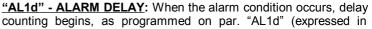
With this mode is possible to program the minimum and the maximum set of "AL1" by "AL1L" and "AL1H" parameters.



LHAb = ABSOLUTE BAND ALARM: The alarm is activated when "AL1L" or goes higher than the alarm threshold set on parameter "AL1H" and will be deactivated when it goes below the value [AL1H HAL1] or when it goes above the value [AL1L + HAL1].

the process value goes below the value [SP1 + AL1L] or goes above than the value [SP1 + AL1H] and will be deactivated when it goes below the value [SP1 + AL1H - HAL1] or when it goes above the value [SP1 + AL1L + HAL1].





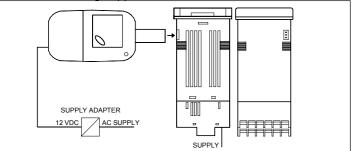
sec.) and the alarm will be activated only after the elapsing of that Group "1SP" (parameters relative to the Set Point) time.

"AL1i" - ALARM ACTIVATION IN CASE OF MEASUREMENT ERROR: This allows one to establish how the alarm have behave in the event of a measurement error (yES=alarm active; no=alarm deactivated).

#### 4.10 - PARAMETERS CONFIGURATION BY "KEY01"

The instrument is equipped with a connector that allows the transfer from and toward the instrument of the functioning parameters through the device **TECNOLOGIC KEY01** with **3 poles** connector. This device it's mainly useable for the serial programming of the instruments which need to have the same parameters configuration or to keep a copy of the programming of an instrument and allow its rapid retransmission.

To use the device KEY01 it's necessary that both device and instrument are being supplied.



To transfer the configuration of an instrument into the device **(UPLOAD)** it is necessary to proceed in the following way:

1) position both dip switch of KEY 01 in the **OFF** mode.

2) connect the device to the instrument TLK plugging the special connector.

3) verify that the instrument and the device are supplied

4) observe the indication led on the device KEY 01: if it results green this means that a configuration is already loaded on the device while if it results green blinking or red blinking this means that it has not been loaded any valid configuration on the device .
5) press the button placed on the device.

6) observe the indication led : after having pressed the button, the led becomes red and therefore, at the end of the data transfer, it becomes green.

7) now it is possible to disconnect the device.

To transfer the configuration loaded on the device onto an instrument of the same family (**DOWNLOAD**), it is necessary to proceed in the following way:

1) position both dip switch of KEY 01 in the **ON** mode.

2) connect the device to an instrument TLK having the same features of the one from which has been downloaded the desired configuration, plugging the special connector.

3) verify that the instrument and the device are supplied

4) observe the indication led on the device KEY 01: it has to result green, because if the led results green blinking or red blinking, this means that on the device it has not been downloaded any valid configuration and therefore it's useless to continue.

5) if the les results green, press the button placed on the device.6) observe the indication led : after having pressed the button, the led becomes red and therefore, at the end of the data transfer, it becomes green.

7) now it is possible to disconnect the device.

For additional info, please have a look at the KEY01 instruction manual.

#### 5 - PROGRAMMABLE PARAMETERS TABLE

Here following are described all the parameters available on the instrument. Some of them could be not present or because they are depending on the type of instrument or because they are automatically disabled as unnecessary.

Par.		Description	Range	Def.	Note
1	SP1	Set Point	SPLL ÷ SPHL	0	
		Low Set Point	-1999 ÷ SPHL	-1999	
3		High Set Point	SPLL ÷ 9999	9999	
		P" (parameters relative t			
-	Par.	Description	Range	Def.	Note
4	SEnS	Probe type:	input C :	J	
		J= thermocoupled J	J/CrAL/S/		
		CrAL= termocoupled K	Ir.J / Ir.CA /		
		S= thermocoupled S	Pt1 / 0.50 /		
		Ir.J= Infrared Sen. IRS	0.60 / 12.60	-	
		J	<u>input E :</u>	Ptc	
		Ir.CA= Infrared Sen.	J/ CrAL/S/		
		IRS K	Ir.J / Ir.CA /		
		Pt1= thermoresistance Pt100	Ptc / ntc / 0.50 / 0.60 /		
		0.50= 050 mV	12.60		
		0.60= 060 mV	<u>input I :</u>	4.20	
		12.60= 1260 mV	0.20 / 4.20	4.20	
		Ptc= thermistor PTC	<u>input V :</u>	0.10	
		KTY81-121	0.1/0.5/1.5	0.10	
		ntc= thermistor NTC	/ 0.10 / 2.10		
		103-AT2	/ 0.10 / 2.10		
		0.20= 020 mA			
		4.20= 420 mA			
		0.1= 01 V			
		0.5=05 V			
		1.5= 15 V			
		0.10= 010 V			
		2.10= 210 V			
5	SSC	Low scale limit in case	-1999 ÷ FSC	0	
		of input with V / I			
		signals			
6	FSC	High scale limit in case	SSC ÷ 9999	100	
		of input with V / I			
		signals			
7	dP	Number of decimal	Pt1 / Ptc / ntc:	0	
		figures	0 / 1		
			<u>norm sig.:</u>		
			0 ÷ 3		
8	Unit	Temperature unit of	°C / °F	°C	
_		measurement			
9	FiL	Input digital filter	0FF÷ 20.0	1.0	
10			Sec.		
10		Measuring Offset	-1999 ÷ 9999	0	
11	rot		0.000 ÷ 2.000	1.000	
		measuring straight line			
12	OPE	Output power in case of		0	
		measuring error	%		
		ut" (parameters relative		_	
	Par.	Description	Range	Def.	Note
13	O1F	Functioning of output 1:	1.rEG / 2.rEG	1.rEG	
		1.rEG= Control Out 1	ALno / ALnc		
		2.rEG=Control Out 2	ALni / OFF		
		ALno= Alarm Out nor-			
		mally opened			
		ALnc= Alarm Out nor-			
		mally closed ALni= Alarm Out nor-			
		mally closed with rever-			
14	O2F	se led func. Functioning of output 2:	1.rEG / 2.rEG	ALno	
14	02F	see "O1F"	ALno / ALnc	ALIIU	
			ALni / OFF		
Group " <sup>1</sup> AL1" (parameters relative to alarm AL1)					
	Par.	Description	Range	Def.	Note
15		Output where alarm	Out1 / Out2 /	Out2	NOLE
13		AL1 is addressed	Out / Out2 / OFF	Juiz	
16	AL1t	Alarm AL1 type:	LoAb / HiAb	LoAb	
10		LoAb= Absolute Low	LHAb / LodE	20/10	
		HiAb= Absolute High			

HiAb= Absolute High HidE / LHdE

LodE= Deviation Low HidE= Deviation BandLodE= Deviation Band17AL1Alarm AL1 thresholdAL1L+ AL1H018AL1LLow threshold band-1999 + AL1H-199918AL1HLow threshold band-1999 + AL1H-199919AL1HHigh threshold bandAL1L+ 9999999919AL1HHigh threshold bandAL1L+ 9999999920HAL1Alarm AL1 for high or low alarmOFF + 9999121AL1dActivation delay of alarm AL1OFF + 99990FF22AL1iAlarm AL1 activation in ncase of measuring errorno / yESnoGroup " J rEG" (parameters relative to the control)Par.DescriptionRangeDef.Note23ContControl type: Pid PID On.FA = ON/OFF saym. On.FS = ON/OFF Neutral ZonePid / On.FAOn.FS / nrNote24FuncFunctioning mode output 1.rEGOFF / 99991-24FuncCompressor Protection of FF 99990sec27AutoAutotuning Fast enable OFF = Not active of Satt at first power on 3 = Start manually 4 = Start at change SetOFF + 999930029PbProportional band0 + 999940-31dErDerivative time OFF + 9999300sec32FuncFunction grading0.01 + 99.991.0033tcr1Cycle time of output 0.1 + 130.010.00-	I	1	UUAb- Abaaluta Dand	I		I I
HidE= Deviation High LHdE= Deviation Band Alarm AL1 threshold       AL1L+ AL1H       0         17       AL1       Alarm AL1 threshold       AL1L+ AL1H       0         18       AL1L       Low threshold band alarm AL1 or Maimum set alarm AL1 activation in no / yES       0FF + 9999       1         20       HAL1       Alarm AL1 activation in case of measuring error       0FF + 9999       0FF         21       AL1d       Alarm AL1 activation in case of measuring error       no       yES       no         23       Cont       Control type: Pid (On.FA Pid= PID       Pid (On.FA On.FS / nr       Pid       Note         24       Func:       Functioning mode output 1.rEG       HEAt / CooL       HEAt       0FF / 1 / 2 / 3 / 4       OFF         27       Auto       Autotuning Fast enable OFF = Not active on alar start at first power on alar start at change Set       FASt / OSC       FASt FASt = FAST OSC = Oscillating       OFF + 9999       300         29       Pb       Proportional band       0 + 9999       40          31       dEr       Derivative time       OFF + 9999       300 <td></td> <th></th> <td>LHAb= Absolute Band</td> <td></td> <td></td> <td></td>			LHAb= Absolute Band			
LHdE= Deviation Band       Image: section of the sectin of the section of the section of the section						
17       AL1       Alarm AL1 threshold       AL1L÷ AL1H       0         18       AL1L       Low threshold band       1999 + AL1H       -1999         19       AL1H       High threshold band       AL1L÷ 9999       9999         alarm AL1 or Minimum set alarm AL1 for high or low alarm       0       9999       1         20       HAL1       Alarm AL1 for high or low alarm       0       0         20       HAL1       Alarm AL1 for high or low alarm       0       0         21       AL1d       Alarm AL1 hysteresis       0FF ÷ 9999       1       0         22       AL1i       Alarm AL1 activation in no / yES no case of measuring error       no       -         Group " <sup>1</sup> rEG" (parameters relative to the control)       Pid       On.FA       Pid         Par.       Description       Range       Def.       Note         23       Cont       Control type:       Pid / On.FA       Pid       On.FS / nr         On.FS = ON/OFF asym.       Or.FS / nr       On.FS / nr       On.FS / nr       Or.FA         24       Func       Functioning mode on 2 sec.       0       sec.       0       1 / 2 / 3 / 4       1         25       HSt       Hysteresis of ON/OFF       0 + 9						
alarm AL1 or Minimum set alarm AL1 for high or low alarmAL1 for high or low alarm19AL1H High threshold band alarm AL1 or Maximum set alarm AL1 or Maximum set alarm AL1 for high or low alarmAL1L + 9999 Sec.999920HAL1 AL1 alarm AL1 hysteresisOFF + 9999 sec.121AL1d Activation delay of alarm AL1OFF + 9999 sec.0FF22AL1i Alarm AL1 activation in case of measuring errorno / yESnoGroup "I rEG" (parameters relative to the control)Par.Description Par.Range OFF sym. On.FS = ON/OFF asym. On.FS = ON/OFF sym. NORF Neutral ZonePidNote23ContControl type: Pid PID On.FS = ON/OFF sym. nr = ON/OFF Neutral ZonePidNote24FuncFunctioning mode output 1.rEGHEAt / CooL of PF + 9999 otime for 2.rEGNOFF / 0FF + 9999 1OFF / 112 / 3 / 426CPdtCompressor Protection OFF + 9999 of time for 2.rEGOFF / sec.OFF / 12 / 3 / 427AutoAutotuning Fast enable OFF / 0FF = Not active on 3 = Start at change SetOFF / sec.OFF / 12 / 3 / 428A.SELAutotuning mode: osC = OscillatingFASt / OSCFASt / sec.29PbProportional band0 + 9999 sec.30.31dErDerivative time osC = OScillating00 + 99.99 sec.1.0032FuQcFuzzy overshoot control0.00 + 90.99 sec.	17	AL1	Alarm AL1 threshold		0	
set alarm AL1 for high or low alarmset alarm AL1 for high alarm AL1 or Maximum set alarm AL1 for high or low alarm $AL1L + 9999$ 9999 $9999$ 20HAL1 Alarm AL1 for high or low alarmOFF + 9999 sec.121AL1d Activation delay of alarm AL1OFF + 9999 sec.0FF22AL1i Alarm AL1 activation in case of measuring errorno / yES sec.noGroup "1 FEG" (parameters relative to the control)TEG" (parameters relative to the control)Par.Description DescriptionRange NoteDef.Note23Cont Control type: Pid PID On.FS = ON/OFF saym. NnFS = ON/OFF Neutral ZonePid / On.FA On.FS / nrPid24Func Functioning mode output 1.rEGHEAt / CooL 0.FF = Not active 1 / 2 / 3 / 4HEAt 0 - Sec.25HSEt HSEt Hysteresis of ON/OFF OFF = Not active on 3 = Start at first power on 2 = Start at change SetOFF / 1 / 2 / 3 / 4OFF28A.SEL Autotuning mode: FASt = FAST OSC = OscillatingOFFF + 9999 9 30030Int29PbProportional band 0 + 99990 + 9999 9 300303131dEr Derivative timeOFF + 9999 9 300303132FuOc Fuzzy overshoot control 1.rEG0.0 + 99.99 9 1.001.0033tcr1 Cycle time of 2.rEG0.1 + 130.0 9.00 + 99.991.0035tcr2 Cycle time of 2.rEG0.1 + 130.0 9.00 + 99.991.0035tcr2Cy	18	AL1L	Low threshold band	-1999 ÷ AL1H	-1999	
or low alarmAL1H19AL1HHigh threshold band alarm AL1 or Maximum set alarm AL1 hysteresisOFF + 9999 sec.20HAL1Alarm AL1 activation in case of measuring errorOFF + 9999 sec.121AL1dActivation delay of case of measuring errorOFF + 9999 sec.0Group "1rEG" (parameters relative to the control)Par.DescriptionRange Note23ContControl type: Pid = PID On.FA = ON/OFF sym. On.FS = ON/OFF sym. On.FS = ON/OFF Neutral ZonePidPid24FuncFunctioning mode output 1.rEGHEAt / CooLHEAt25HSEtHysteresis of ON/OFF OFF = Not active on 1 = Start each power on 2 = Start at first power on 3 = Start manually 4 = Start at change SetOFF / 1 / 2 / 3 / 4OFF28A.SELAutoting mode: Autouning mode of the sec.FASt / OSCFASt FASt = FAST OSC = OscillatingFASt / OSC29PbProportional band0 + 9999300astart sec.31dErDerivative time of the sec.OFF + 9999 soo3033tcr1Cycle time of 0.rEG OFF + 99990.00sec.33tcr1Cycle time of 0.rEG of the sec.0.00 + 2.000.5033tcr1Cycle time of 2.rEG OSC = 0.1 + 130.020.0sec.34PtatPower ratio 2.rEG of the sec.0.1 + 130.0 <th></th> <th></th> <th></th> <th></th> <th></th> <th></th>						
19AL1HHigh thresholdband alarm AL1 or Maximum 						
alarm AL1 or Maximum set alarm AL1 for high or low alarmImage: constraint of the set of	10			AL 11 ÷ 0000	0000	
set alarm AL1 for high or low alarmImage: set alarm AL1 hysteresis OFF + 9999OFF + 9999120HAL1 Alarm AL1 hysteresis alarm AL1OFF + 9999 sec.OFF21AL1dActivation delay of case of measuring errorNo / yESno22AL1iAlarm AL1 activation in no / yESnoImage: sec.Note22AL1iAlarm AL1 activation in no / yESnoImage: sec.Note23ContControl type: pid = PID On.FA = ON/OFF asym. On.FS = ON/OFF sym. nr = ON/OFF Neutral ZonePid / On.FA On.FS / nrPid24FuncFunctioning mode output 1.rEGHEAt / CooLHEAt25HSEtHystersis of ON/OFF oontrol0 + 9999126CPdtCompressor Protection on 2= Start at first power on 3= Start manually 4= Start at change SetOFF / 1 / 2 / 3 / 4OFF28A.SELAutouning mode: ool 2= Start at change SetFASt / OSCFASt29PbProportional band0 + 99994030IntIntegral time sec.OFF + 9999 300 sec.3031dErDerivative time or 2.rEGSec.3032FuOcFuzzy overshoot control0.00 + 9.9991.0033tcr1Cycle time of 2.rEG Sec.0.1 + 130.0 Sec.20.031dErDerivative time or 2.rEGSec.3033tcr2Cycle time of 2.rEG Sec.0.1 + 130.0 Sec.1.00 <t< th=""><th>13</th><th></th><th></th><th>ALTE - 55555</th><th>5555</th><th></th></t<>	13			ALTE - 55555	5555	
20       HAL1       Alarm AL1 hysteresis       OFF ÷ 9999       1         21       AL1d       Activation delay of alarm AL1       OFF ÷ 9999       OFF         22       AL1i       Alarm AL1 activation in case of measuring error       no / yES       no         Group "1FEG" (parameters relative to the control)       Par.       Description       Range       Def.       Note         23       Cont       Control type: pid = PID       On.FA       Pid       On.FS / nr       Note         24       Func       Functioning mode output 1.rEG       OFF + 9999       0       Extra table       Def.       Note         25       HSEt       Hysteresis of ON/OFF       0 + 9999       0       sec.						
21       AL1d       Activation delay of alarm AL1       OFF + 9999 sec.       OFF         22       AL1i       Alarm AL1 activation in case of measuring error       no       yes         Group "1 rEG" (parameters relative to the control)       Par.       Description       Range       Def.       Note         23       Cont       Control type: pid / On.FA       Pid       On.FS       Note         24       Func       Functioning mode output 1.rEG       Pid / On.FS       0 + 9999       1         25       HSEt       Hysteresis of ON/OFF output 1.rEG       0 + 9999       0       sec.         26       CPdt       Compressor Protection output 1.rEG       OFF + 9999       0       sec.         26       CPdt       Compressor Protection on 2 = Start at first power on 2 = Start at first power on 3 = Start manually 4 = Start at change Set       0/FF / OFF       OFF / OFF         28       A.SEL       Autotuning mode: FAST / OSC       FASt / SST / OSC = Oscillating       999       30         29       Pb       Proportional band       0 + 9999       30       sec.       30         31       dEr       Derivative time       OFF + 9999 osc.       30       sec.       30         32       Fuoc       Fuzzy overshoot control       <						
alarm AL1       sec.         22       AL1i       Alarm AL1 activation in case of measuring error       no / yES       no         Group "1 rEG" (parameters relative to the control)       Par.       Description       Range       Def.       Note         23       Cont       Control type: On.FA Pid PID       Pid / On.FA On.FS / nr       Pid       Pid       Note         23       Cont       Control type: On.FS = ON/OFF asym. On.FS = ON/OFF Neutral Zone       Pid       On.FS / nr       Note         24       Func       Functioning mode output 1.rEG       HEAt / Cool.       HEAt       HEAt         25       HSEt       Hysteresis of ON/OFF ose.       0 ÷ 9999       1					-	
22       AL1i       Alarm AL1 activation in case of measuring error       no       no         Group "1 rEG" (parameters relative to the control)       Par.       Description       Range       Def.       Note         23       Cont       Control type: Pid / On.FA       Pid / On.FS / nr       On.FS - ON/OFF asym. On.FS = ON/OFF Neutral Zone       Pid / On.FS / nr       Pid       Pid         24       Func       Functioning mode output 1.rEG       HEAt / Cool.       HEAt       HEAt         25       HSEt       Hysteresis of ON/OFF othe sym. Inre ON/OFF set and Zone       OFF + 9999       0       Image: Control       OFF + 9999       0         26       CPdt       Compressor Protection OFF + 9999       0 sec.       OFF       0       1 / 2 / 3 / 4       Image: Control       0FF + 9999       0         27       Auto       Autotuning Fast enable OFF / 1 Start acch power on 2 = Start at first power on 2 = Start at change Set       0FF + 9999       300       Image: Control Sec.       Sec. <td>21</td> <th>AL1d</th> <td></td> <td></td> <td>OFF</td> <td></td>	21	AL1d			OFF	
case of measuring error         Group " <sup>1</sup> rEG" (parameters relative to the control)         Par.       Description       Range       Def.       Note         23       Cont       Control type: Pid / On.FA       Pid / On.FA       Did         23       Cont       Control type: Pid / On.FA       Pid       Note         24       Func       Functioning mode output 1.rEG       O ÷ 9999       1         25       HStet       Hysteresis of ON/OFF control       OFF ÷ 9999       0         26       CPdt       Compressor Protection OFF = Not active       OFF / 1 / 2 / 3 / 4       OFF         27       Auto       Autotuning Fast enable OFF = Not active       OFF / 1 / 2 / 3 / 4       OFF         28       A.SEL       Autotuning mode: FASt at at change Set       FASt / OSC       FASt         28       A.SEL       Autotuning mode: FASt = FAST OSC = Oscillating       Sec.       30 <t< td=""><td>22</td><th>AL 1i</th><td></td><td></td><td><b>no</b></td><td></td></t<>	22	AL 1i			<b>no</b>	
Group " ${}^{1}$ rEG" (parameters relative to the control)Par.DescriptionRangeDef.Note23ContControl type: Pid PID On.FA= ON/OFF asym. On.FS= ON/OFF sym. nr= ON/OFF Neutral ZonePid / On.FAPid On.FS / nrPid24FuncFunctioning mode output 1.rEGHEAt / CooLHEAt25HSEtHysteresis of ON/OFF control0 ÷ 9999126CPdtCompressor Protection OFF = Not active 1 = Start each power on 2 = Start at first power on 3 = Start manually 4 = Start at change SetOFF / 1 / 2 / 3 / 4OFF28A.SELAutotuning mode: FASt = FAST OSC = OscillatingFASt / OSCFASt29PbProportional band0 ÷ 9999300 sec.31dErDerivative time 1.rEGOFF + 9999300 sec.34PratPower ratio 2rEg / 1rEg0.01 ÷ 99.991.0035tcr1Cycle time of output 1.rEG0.1 ÷ 130.0 sec.10.034PratPower ratio 2rEg / 1rEg0.01 ÷ 99.991.0035tcr2Cycle time of 2.rEG0.1 ÷ 130.0 sec.10.036rSManual reset 1.rEG-100.0 ÷ 100.0 sec.10.035tcr2Cycle time of 2.rEG0.1 ÷ 199.991.0036rSManual reset 1.rEG-100.0 ÷ 100.00.036rSManual reset-100.0 ÷ 99.99InF37SLorGradient of ramp: InF = Ramp not active <td>22</td> <th></th> <td></td> <td>107 yL3</td> <td>no</td> <td></td>	22			107 yL3	no	
Par.DescriptionRangeDef.Note23ContControl type: Pid PID On.FA = ON/OFF asym. On.FS = ON/OFF sym. nr= ON/OFF Neutral ZonePid / On.FA On.FS / nrPid24FuncFunctioning mode output 1.rEGHEAt / CooLHEAt25HSEtHysteresis of ON/OFF control $0 \div 9999$ 126CPdtCompressor Protection time for 2.rEGOFF / sec.0FF / 1 / 2 / 3 / 40FF27AutoAutotuning Fast enable OFF = Not active 1 = Start each power on 2 = Start at first power on 3 = Start manually 4 = Start at change SetFASt / OSCFASt28A.SELAutotuning mode: proportional bandFASt / OSCFAStFASt29PbProportional band $0 \div 9999$ 300 sec.sec.31dErDerivative time 1./cycle time of output 1.rEG $0.1 \div 130.0$ sec.20.0 sec.20.0 sec.33tcr1Cycle time of output 1.rEG $0.1 \div 130.0$ sec.10.020.0 sec.34PratPower ratio 2rEg / 1rEg Vicel time of 2.rEG $0.1 \div 19.99$ 1.001.0035tcr2Cycle time of 2.rEG Vicel time of 2.rEG $0.1 \div 130.0$ (0.0 $\div 99.99$ 1.0036rS Manual reset $-100.0 \div 100.0$ (1.F= mamp not active / 1.F= mamp not active $0.00 \div 99.99$ / 1.FInf36rS ABAManual reset ABA $-100.0 \div 99.99$ 1.0037SLor Gradient of ramp: InF= Ramp not active<	Gro	up " <sup>1</sup> r		to the control)		J
23       Cont       Control type: Pid / On.FA       Pid / On.FA       Pid         0n.FA= ON/OFF asym. On.FS= ON/OFF sym. nr= ON/OFF Neutral Zone       Pid / On.FA       Pid         24       Func       Functioning mode output 1.rEG       HEAt / CooL       HEAt         25       HSEt       Hysteresis of ON/OFF control       0 ÷ 9999       1         26       CPdt       Compressor       Protection time for 2.rEG       OFF / sec.       0FF / 1 / 2 / 3 / 4       0FF         27       Auto       Autotuning Fast enable OFF = Not active 1 = Start each power on 2 = Start at first power on 3 = Start manually 4 = Start at change Set       OFF       0FF         28       A.SEL       Autotuning mode: FASt = FAST OSC = Oscillating       FASt / OSC       FASt         30       Int       Integral time       0FF ÷ 9999       300 sec.         31       dEr       Derivative time       OFF ÷ 9999       30 sec.         32       FuOC       Fuzzy overshoot control       0.00 ÷ 2.00       0.50         33       tcr1       Cycle time of 2.rEG       0.1 + 130.0       10.0         35       tcr2       Cycle time of 2.rEG       0.1 + 130.0       10.0         36       rS       Manual reset       -100.0 + 100.0       0.0 <t< td=""><td></td><th></th><td></td><td></td><td>Def.</td><td>Note</td></t<>					Def.	Note
On.FA= ON/OFF asym. On.FS= ON/OFF Neutral ZoneHEAt / CoolHEAt24FuncFunctioning mode output 1.rEGHEAt / CoolHEAt25HSEtHysteresis of ON/OFF control $0 \div 9999$ 126CPdtCompressor Protection optime for 2.rEGOFF $\div 9999$ 027AutoAutotuning Fast enable OFF = Not active 1 = Start each power on 2 = Start at first power on 3 = Start manually 4 = Start at change SetOFF / 1 / 2 / 3 / 4OFF28A.SELAutotuning mode: FASt = FAST OSC = OscillatingFASt / OSC Sec.FASt29PbProportional band $0 \div 9999$ 4030IntIntegral timeOFF $\div 9999$ Sec.30031dErDerivative time sec.OFF $\div 9999$ Sec.30032FuOcFuzzy overshoot control $0.00 \div 2.00$ Sec. $0.50$ 31dErDerivative time sec. $0FF \div 9999$ Sec. $1.00$ 32FuOcFuzzy overshoot control $0.00 \div 2.00$ Sec. $0.50$ 33tcr1Cycle time of output sec. $0.1 \div 130.0$ Sec. $1.00$ 35tcr2Cycle time of 2.rEG Cycle time of 2.rEG $0.1 \div 130.0$ Sec. $1.00$ 36rS Manual reset InF = Ramp not active InF and not active $1.00 \div 99.99$ $1.00$ 36rS Manual reset $-100.0 \div 100.0$ ( $0.00 \div 99.99$ ) $1.01$ 37SLor Gradient of ramp: InF = Ramp not active InF = Ramp not active $0.0$			Control type:	Pid / On.FA	Pid	
On.FS= ON/OFF sym. nr= ON/OFF Neutral ZoneHEAt / Cool.HEAt24FuncFunctioning mode output 1.rEGHEAt / Cool.HEAt25HSEtHysteresis of ON/OFF control $0 \div 9999$ 126CPdtCompressor Protection oppressor ProtectionOFF ÷ 9999 sec.027AutoAutotuning Fast enable OFF = Not active on 2 = Start at first power on 3 = Start manually 4 = Start at change SetOFF / 1 / 2 / 3 / 4OFF28A.SELAutotuning mode: FASt = FAST OSC = OscillatingFASt / OSC sec.FASt29PbProportional band $0 \div 9999$ 3030IntIntegral time sec.OFF ÷ 9999 sec.3031dErDerivative time sec.OFF ÷ 9999 sec.3032FuOcFuzzy overshoot control 1.rEG $0.0 \div 9999$ 1.0033tcr1Cycle time of output 1.rEG $0.1 \div 130.0$ sec.20.034PratPower ratio 2rEg / 1rEg 0.01 ÷ 99.991.0035tcr2Cycle time of 2.rEG med of 2.rEG $0.1 \div 130.0$ sec.10.036rS manual reset InF= Ramp not active of 2.rEG $0.00 \div 99.99$ of 1.nEInF37SLorGradient of ramp: (parameters relative to the user interface)NotePar.DescriptionRange ContDef.Note38AdEShift value for the shiftOFF99992				On.FS / nr		
anr = ON/OFF Neutral Zone       nr = ON/OFF Neutral Zone       Heat / Cool       HEAt         24       Func       Functioning mode output 1.rEG       HEAt / Cool       HEAt         25       HSEt       Hysteresis of ON/OFF control       0 ÷ 9999       1         26       CPdt       Compressor Protection time for 2.rEG       OFF ÷ 9999 sec.       0         27       Auto       Autotuning Fast enable OFF = Not active an       OFF / 1 / 2 / 3 / 4       OFF         27       Auto       Autotuning mode: OFF = Not active on 3 = Start manually 4 = Start at change Set       OFF / 1 / 2 / 3 / 4       OFF         28       A.SEL       Autotuning mode: FASt = FAST OSC = Oscillating       FASt / OSC       FASt         29       Pb       Proportional band       0 ÷ 9999       30         30       Int       Integral time       OFF ÷ 9999 Sec.       30         31       dEr       Derivative time       OFF ÷ 9999 Sec.       30         33       tcr1       Cycle time of output       0.1 ÷ 130.0 Sec.       20.0 Sec.         34       Prat       Power ratio 2rEg / 1rEg       0.01 ÷ 99.99       1.00         35       tcr2       Cycle time of 2.rEG       0.1 ÷ 130.0 Sec.       10.0 Sec.       10.0 Sec.         36			On.FA= ON/OFF asym.			
ZoneHEAt / CoolHEAt24FuncFunctioning mode output 1.rEGHEAt / CoolHEAt25HSEtHysteresis of ON/OFF control0 ÷ 9999126CPdtCompressor Protection ompressor ProtectionOFF ÷ 9999 sec.027AutoAutotuning Fast enable OFF = Not active 1 = Start each power on 2 = Start at first power on 3 = Start manually 4 = Start at change SetOFF / 1 / 2 / 3 / 4OFF28A.SELAutotuning mode: FASt = FAST OSC = OscillatingFASt / OSC Sec.FASt29PbProportional band0 ÷ 99994030IntIntegral time sec.OFF + 9999 Sec.30031dErDerivative time 1.rEGOFF + 9999 Sec.30033tcr1Cycle time of output 1.rEG0.1 ÷ 130.0 Sec.20.034PratPower ratio 2rEg / 1rEg Sec.0.1 ÷ 99.991.0035tcr2Cycle time of 2.rEG0.1 ÷ 130.0 Sec.10.036rSManual reset InF= Ramp not active InF= Ramp not active / InF unit/min100.0 ÷ 100.0 Sec.0.036rSManual reset Sec100.0 ÷ 100.0 Sec.0.030036rSManual reset Sec100.0 ÷ 100.0 Sec.0.030037SLorGradient of ramp : InF= Ramp not active / InF unit/min.InFNote38AdEShift value for the shiftOFF999922 <td></td> <th></th> <td></td> <td></td> <td></td> <td></td>						
24       Func       Functioning mode output 1.rEG       HEAt / CooL       HEAt         25       HSEt       Hysteresis of ON/OFF control       0 ÷ 9999       1         26       CPdt       Compressor Protection of Compressor Protection of time for 2.rEG sec.       OFF + 9999       0         27       Auto       Autotuning Fast enable OFF / Not active 1 / 2 / 3 / 4       OFF       0FF         28       A.SEL       Autotuning mode: FASt power on 3= Start manually 4= Start at change Set       FASt = FAST OSC = Oscillating       FASt = FAST         29       Pb       Proportional band       0 ÷ 9999       300 sec.       300 sec.         31       dEr       Derivative time       OFF ÷ 9999       300 sec.       300 sec.         32       FuOC       Fuzzy overshoot control       0.00 ÷ 2.00       0.50       33         32       FuOC       Fuzzy overshoot control       0.00 ÷ 2.00       0.50       33         33       tcr1       Cycle time of 0.rEG       0.1 ÷ 130.0       20.0       31         34       Prat       Power ratio 2rEg / 1rEg       0.01 ÷ 99.99       1.00       35         36       rS       Manual reset       -100.0 ÷ 100.0       0.0       %         37       SLor       Gradient						
25       HSEt       Hysteresis of ON/OFF control       0 ÷ 9999       1         26       CPdt       Compressor Protection for 2.rEG       OFF ÷ 9999       0         27       Auto       Autotuning Fast enable OFF / 1 / 2 / 3 / 4       OFF         27       Auto       Autotuning Fast enable OFF / 1 / 2 / 3 / 4       OFF         28       A.SEL       Autotuning mode: FASt enable OSC = 0 scillating       FASt = FAST OSC = 0 scillating         29       Pb       Proportional band       0 ÷ 9999       30         30       Int       Integral time       OFF ÷ 9999       30         31       dEr       Derivative time       OFF ÷ 9999       30         32       FuOc       Fuzzy overshoot control       0.00 ÷ 2.00       0.50         33       tcr1       Cycle time of output       0.1 ÷ 130.0       20.0         34       Prat       Power ratio 2rEg / 1rEg       0.01 ÷ 99.99       1.00         35       tcr2       Cycle time of 2.rEG       0.1 ÷ 130.0       10.0         36       rS       Manual reset       -100.0 ÷ 100.0       0.0         37       SLor       Gradient of ramp: InF= Ramp not active       1.00 ÷ 99.99       InF         37       SLor       Gradie	24	Func		HEAt / CooL	HEAt	
26       Control       OFF÷ 9999 sec.       0         27       Auto       Autotuning Fast enable OFF = Not active 1 = Start each power on 2 = Start at first power on 3 = Start manually 4 = Start at change Set       OFF / 1 / 2 / 3 / 4       OFF         28       A.SEL       Autotuning mode: FASt = FAST OSC = Oscillating       FASt / OSC FASt       FASt         29       Pb       Proportional band       0 ÷ 9999 sec.       300         30       Int       Integral time       OFF ÷ 9999 sec.       300         31       dEr       Derivative time       OFF ÷ 9999 sec.       300         32       FuOc       Fuzzy overshoot control       0.00 ÷ 2.00       0.50         33       tcr1       Cycle time of output 1.rEG       0.1 ÷ 130.0 sec.       20.0         34       Prat       Power ratio 2rEg / 1rEg       0.01 ÷ 99.99       1.00         35       tcr2       Cycle time of 2.rEG       0.1 ÷ 130.0 sec.       10.0         36       rS       Manual reset       -100.0 ÷ 100.0 %       0.0         37       SLor       Gradient of ramp: InF= Ramp not active       0.00 ÷ 99.99 / 1nF       InF         38       AdE       Shift value for the shift       OFF9999       2			output 1.rEG			
26       CPdt       Compressor Protection films for 2.rEG       OFF + 9999 sec.       0         27       Auto       Autotuning Fast enable OFF / OFF = Not active 1 / 2 / 3 / 4       OFF / 1 / 2 / 3 / 4       0         28       A.SEL       Autoning Fast enable on 2= Start at first power on 2= Start at change Set       FASt / OSC       FASt         28       A.SEL       Autotuning mode: FASt = COSC = Oscillating       FASt = FAST OSC = OSCIllating       FASt = Start at change Set         29       Pb       Proportional band       0 ÷ 9999       300 sec.         30       Int       Integral time       OFF ÷ 9999 osc.       30 sec.         31       dEr       Derivative time       OFF ÷ 9999 osc.       30 sec.         33       tcr1       Cycle time of output 1.rEG sec.       0.01 ÷ 90.99 1.00         34       Prat       Power ratio 2rEg / 1rEg 0.01 ÷ 99.99 1.00       30 sec.         35       tcr2       Cycle time of 2.rEG 0.1 ÷ 130.0 sec.       10.0 sec.         36       rS       Manual reset       -100.0+100.0 sec.       0.0 %         37       SLor       Gradient of ramp: 0.00 ÷ 90.99 isec.       1.nF         38       AdE       Shift value for the shift       OFF9999 2 <td>25</td> <th>HSEt</th> <td></td> <td>0 ÷ 9999</td> <td>1</td> <td></td>	25	HSEt		0 ÷ 9999	1	
time for 2.rEG       sec.         27       Auto       Autotuning Fast enable OFF = Not active 1 = Start each power on 2 = Start at first power on 3 = Start manually 4 = Start at change Set       OFF / 1 / 2 / 3 / 4       OFF         28       A.SEL       Autotuning mode: FASt = FAST OSC = Oscillating       FASt / OSC       FASt         29       Pb       Proportional band       0 ÷ 9999       40         30       Int       Integral time       OFF ÷ 9999       300         31       dEr       Derivative time       OFF ÷ 9999       30         33       tcr1       Cycle time of output 1.rEG       0.1 ÷ 130.0       20.0         34       Prat       Power ratio 2rEg / 1rEg       0.01 ÷ 99.99       1.00         35       tcr2       Cycle time of 2.rEG       0.1 ÷ 130.0       10.0         36       rS       Manual reset       -100.0÷100.0       0.0         37       SLor       Gradient of ramp: InF= Ramp not active       0.00 ÷ 99.99       InF         38       AdE       Shift value for the shift       OFF9999       2	26	CDdt			0	
27       Auto       Autotuning Fast enable OFF = Not active 1 = Start each power on 2 = Start at first power on 3 = Start manually 4 = Start at change Set       0 FF / 1 / 2 / 3 / 4       OFF         28       A.SEL       Autotuning mode: FASt = FAST OSC = Oscillating       FASt / OSC       FASt         29       Pb       Proportional band       0 ÷ 9999       40         30       Int       Integral time       OFF ÷ 9999       300 sec.         31       dEr       Derivative time       OFF ÷ 9999       30         32       FuOc       Fuzzy overshoot control       0.00 ÷ 2.00       0.50         33       tcr1       Cycle time of output 1.rEG       0.1 ÷ 130.0       20.0         34       Prat       Power ratio 2rEg / 1rEg       0.01 ÷ 99.99       1.00         35       tcr2       Cycle time of 2.rEG       0.1 ÷ 130.0       10.0         36       rS       Manual reset       -100.0÷100.0       0.0         37       SLor       Gradient of ramp: InF= Ramp not active       0.00 ÷ 99.99       InF         38       AdE       Shift value for the shift       OFF9999       2	20	CPat			0	
1 = Start each power on 2= Start at first power on 3= Start manually 4= Start at change SetImage: Start manually 4= Start at change Set28A.SELAutotuning mode: FASt = FAST OSC = OscillatingFASt / OSCFASt29PbProportional band0 ÷ 99994030IntIntegral timeOFF ÷ 9999 sec.300 sec.31dErDerivative timeOFF ÷ 9999 sec.3032FuOcFuzzy overshoot control0.00 ÷ 2.00 sec.0.5033tcr1Cycle time of output 1.rEG0.1 ÷ 130.0 sec.20.0 sec.34PratPower ratio 2rEg / 1rEg Sec.0.01 ÷ 99.99 sec.1.0035tcr2Cycle time of 2.rEG Sec.0.1 ÷ 130.0 sec.10.0 sec.36rSManual reset-100.0 ÷ 100.0 %0.0 %37SLorGradient of ramp: InF= Ramp not active0.00 ÷ 99.99 / InF unit/min.InFDescription38AdEShift value for the shiftOFF99992	27	Auto		OFF /	OFF	
2= Start at first power on 3= Start manually 4= Start at change Set       Image: Start manually 4= Start at change Set         28       A.SEL       Autotuning mode: FASt = FAST OSC = Oscillating       FASt / OSC       FASt         29       Pb       Proportional band       0 ÷ 9999       40         30       Int       Integral time       OFF ÷ 9999       300 sec.         31       dEr       Derivative time       OFF ÷ 9999       30         32       FuOc       Fuzzy overshoot control       0.00 ÷ 2.00       0.50         33       tcr1       Cycle time of output       0.1 ÷ 130.0       20.0         34       Prat       Power ratio 2rEg / 1rEg       0.01 ÷ 99.99       1.00         35       tcr2       Cycle time of 2.rEG       0.1 ÷ 130.0       10.0         36       rS       Manual reset       -100.0÷100.0       0.0         37       SLor       Gradient of ramp: InF= Ramp not active       0.00 ÷ 99.99       InF         38       AdE       Shift value for the shift       OFF9999       2				1/2/3/4		
on 3= Start manually 4= Start at change Set       FASt         28       A.SEL       Autotuning mode: FASt = FAST OSC = Oscillating       FASt / OSC       FASt         29       Pb       Proportional band       0 ÷ 9999       40         30       Int       Integral time       OFF ÷ 9999       300 sec.         31       dEr       Derivative time       OFF ÷ 9999       30         32       FuOc       Fuzzy overshoot control       0.00 ÷ 2.00       0.50         33       tcr1       Cycle time of output       0.1 ÷ 130.0       20.0         34       Prat       Power ratio 2rEg / 1rEg       0.01 ÷ 99.99       1.00         35       tcr2       Cycle time of 2.rEG       0.1 ÷ 130.0       10.0         36       rS       Manual reset       -100.0÷100.0       0.0         37       SLor       Gradient of ramp: InF= Ramp not active       0.00 ÷ 99.99       InF         38       AdE       Shift value for the shift       OFF9999       2						
3= Start manually 4= Start at change SetFASt28A.SELAutotuning mode: FASt = FAST OSC = OscillatingFASt / OSCFASt29PbProportional band $0 \div 9999$ 4030IntIntegral timeOFF $\div 9999$ 300 sec.31dErDerivative timeOFF $\div 9999$ 30 sec.32FuOcFuzzy overshoot control $0.00 \div 2.00$ $0.50$ 33tcr1Cycle time of output $1.rEG$ $0.1 \div 130.0$ sec. $20.0$ sec.34PratPower ratio $2rEg / 1rEg$ $0.01 \div 99.99$ $1.00$ 35tcr2Cycle time of $2.rEG$ $0.1 \div 130.0$ sec. $10.0$ sec.36rSManual reset $-100.0 \div 100.0$ $\%$ $0.0$ $\%$ 37SLorGradient of ramp: InF= Ramp not active $0.00 \div 99.99$ / InF unit/min.InFGroup " <sup>1</sup> PAn" (parameters relative to the user interface)Par.DescriptionRangeDef.38AdEShift value for the shiftOFF999922			-			
4= Start at change Set       FASt         28       A.SEL       Autotuning mode: FASt = FAST OSC = Oscillating       FASt / OSC       FASt         29       Pb       Proportional band       0 ÷ 9999       40         30       Int       Integral time       OFF ÷ 9999       300         31       dEr       Derivative time       OFF ÷ 9999       30         32       FuOc       Fuzzy overshoot control       0.00 ÷ 2.00       0.50         33       tcr1       Cycle time of output       0.1 ÷ 130.0       20.0         34       Prat       Power ratio 2rEg / 1rEg       0.01 ÷ 99.99       1.00         35       tcr2       Cycle time of 2.rEG       0.1 ÷ 130.0       10.0         36       rS       Manual reset       -100.0÷100.0       0.0         37       SLor       Gradient of ramp: InF= Ramp not active       0.00 ÷ 99.99       InF         78       Manual reset relative to the user interface)       Par.       Description       Range       Def.       Note         38       AdE       Shift value for the shift       OFF9999       2       2						
FASt = FAST OSC = Oscillating29PbProportional band $0 \div 9999$ 4030IntIntegral timeOFF $\div 9999$ 300 sec.31dErDerivative timeOFF $\div 9999$ 30 sec.32FuOcFuzzy overshoot control $0.00 \div 2.00$ $0.50$ 33tcr1Cycle time of output $1.rEG$ $0.1 \div 130.0$ sec. $20.0$ sec.34PratPower ratio $2rEg / 1rEg$ $0.01 \div 99.99$ $1.00$ 35tcr2Cycle time of $2.rEG$ $0.1 \div 130.0$ sec. $10.0$ sec.36rSManual reset $-100.0 \div 100.0$ $\%$ $0.0$ $\%$ 37SLorGradient of ramp: InF= Ramp not active $0.00 \div 99.99$ / InF unit/min.InFGroup " <sup>1</sup> PAn" (parameters relative to the user interface)Par.DescriptionRangeDef.Note38AdEShift value for the shiftOFF999922						
OSC = Oscillating         OSC = Oscillating           29         Pb         Proportional band         0 ÷ 9999         40           30         Int         Integral time         OFF ÷ 9999         300           31         dEr         Derivative time         OFF ÷ 9999         30           31         dEr         Derivative time         OFF ÷ 9999         30           32         FuOc         Fuzzy overshoot control         0.00 ÷ 2.00         0.50           33         tcr1         Cycle time of output         0.1 ÷ 130.0         20.0           34         Prat         Power ratio 2rEg / 1rEg         0.01 ÷ 99.99         1.00           35         tcr2         Cycle time of 2.rEG         0.1 ÷ 130.0         10.0           36         rS         Manual reset         -100.0 ÷ 100.0         0.0           37         SLor         Gradient of ramp: InF= Ramp not active         / InF unit/min.         InF           Group " <sup>1</sup> PAn" (parameters relative to the user interface)         Par.         Description         Range         Def.         Note           38         AdE         Shift value for the shift         OFF9999         2	28	A.SEL		FASt / OSC	FASt	
29         Pb         Proportional band         0 ÷ 9999         40           30         Int         Integral time         OFF ÷ 9999         300         sec.           31         dEr         Derivative time         OFF ÷ 9999         30         sec.           31         dEr         Derivative time         OFF ÷ 9999         30         sec.           32         FuOc         Fuzzy overshoot control         0.00 ÷ 2.00         0.50           33         tcr1         Cycle time of output         0.1 ÷ 130.0         20.0           34         Prat         Power ratio 2rEg / 1rEg         0.01 ÷ 99.99         1.00           35         tcr2         Cycle time of 2.rEG         0.1 ÷ 130.0         10.0           36         rS         Manual reset         -100.0÷100.0         0.0           37         SLor         Gradient of ramp: InF= Ramp not active         / InF unit/min.         InF           Group " <sup>1</sup> PAn" (parameters relative to the user interface)         Par.         Description         Range         Def.         Note           38         AdE         Shift value for the shift         OFF9999         2         1						
30         Int         Integral time         OFF ÷ 9999 sec.         300 sec.           31         dEr         Derivative time         OFF ÷ 9999 sec.         30 sec.           32         FuOc         Fuzzy overshoot control         0.00 ÷ 2.00         0.50           33         tcr1         Cycle time of output 1.rEG         0.1 ÷ 130.0         20.0           34         Prat         Power ratio 2rEg / 1rEg         0.01 ÷ 99.99         1.00           35         tcr2         Cycle time of 2.rEG         0.1 ÷ 130.0 sec.         10.0           36         rS         Manual reset         -100.0 ÷ 100.0 %         10.0           37         SLor         Gradient of ramp: InF= Ramp not active         0.00 ÷ 99.99 / InF unit/min.         InF           Group " <sup>1</sup> PAn" (parameters relative to the user interface)         Par.         Description         Range         Def.         Note           38         AdE         Shift value for the shift         OFF9999         2         1	20	Dh		0 ÷ 0000	40	
Sec.         sec.           31         dEr         Derivative time         OFF÷ 9999         30           32         FuOc         Fuzzy overshoot control         0.00 ÷ 2.00         0.50           33         tcr1         Cycle time of output         0.1 ÷ 130.0         20.0           34         Prat         Power ratio 2rEg / 1rEg         0.01 ÷ 99.99         1.00           35         tcr2         Cycle time of 2.rEG         0.1 ÷ 130.0         10.0           36         rS         Manual reset         -100.0÷100.0         0.0           37         SLor         Gradient of ramp: InF= Ramp not active         / InF unit/min.         InF           Group " <sup>1</sup> PAn" (parameters relative to the user interface)         Par.         Description         Range         Def.         Note           38         AdE         Shift value for the shift         OFF9999         2         1						
31       dEr       Derivative time       OFF÷ 9999 sec.       30 sec.         32       FuOc       Fuzzy overshoot control       0.00 ÷ 2.00       0.50         33       tcr1       Cycle time of output 1.rEG       0.1 ÷ 130.0       20.0         34       Prat       Power ratio 2rEg / 1rEg       0.01 ÷ 99.99       1.00         35       tcr2       Cycle time of 2.rEG       0.1 ÷ 130.0 sec.       10.0         36       rS       Manual reset       -100.0÷100.0 %       0.0         37       SLor       Gradient of ramp: InF= Ramp not active       0.00 ÷ 99.99 / InF unit/min.       InF         Group " <sup>1</sup> PAn" (parameters relative to the user interface)       Par.       Description       Range       Def.       Note         38       AdE       Shift value for the shift       OFF9999       2       2					500	
32         FuOc         Fuzzy overshoot control         0.00 ÷ 2.00         0.50           33         tcr1         Cycle time of output 1.rEG         0.1 ÷ 130.0 sec.         20.0           34         Prat         Power ratio 2rEg / 1rEg         0.01 ÷ 99.99         1.00           35         tcr2         Cycle time of 2.rEG         0.1 ÷ 130.0 sec.         10.0           36         rS         Manual reset         -100.0 ÷ 100.0 %         0.0           37         SLor         Gradient of ramp: InF= Ramp not active         / InF unit/min.         InF           Group " <sup>1</sup> PAn" (parameters relative to the user interface)           Par.         Description         Range         Def.           38         AdE         Shift value for the shift         OFF9999         2	31	dEr	Derivative time		30	
33       tcr1       Cycle time of output 1.rEG       0.1 ÷ 130.0 sec.       20.0         34       Prat       Power ratio 2rEg / 1rEg       0.01 ÷ 99.99       1.00         35       tcr2       Cycle time of 2.rEG       0.1 ÷ 130.0 sec.       10.0         36       rS       Manual reset       -100.0÷100.0 %       0.0         37       SLor       Gradient of ramp: InF= Ramp not active       0.00 ÷ 99.99 / InF unit/min.       InF         Group " <sup>1</sup> PAn" (parameters relative to the user interface)       Par.       Description       Range       Def.       Note         38       AdE       Shift value for the shift       OFF9999       2       2			_			
1.rEG       sec.         34       Prat       Power ratio 2rEg / 1rEg       0.01 ÷ 99.99       1.00         35       tcr2       Cycle time of 2.rEG       0.1 ÷ 130.0       10.0         36       rS       Manual reset       -100.0÷100.0       0.0         37       SLor       Gradient of ramp: InF= Ramp not active       0.00 ÷ 99.99       InF         Group " <sup>1</sup> PAn" (parameters relative to the user interface)       Par.       Description       Range       Def.       Note         38       AdE       Shift value for the shift       OFF9999       2       1						
34         Prat         Power ratio         2rEg / 1rEg         0.01 ÷ 99.99         1.00           35         tcr2         Cycle time of 2.rEG         0.1 ÷ 130.0 sec.         10.0         10.0           36         rS         Manual reset         -100.0÷100.0 %         0.0         0.0           37         SLor         Gradient of ramp: InF= Ramp not active         0.00 ÷ 99.99 / InF unit/min.         InF           Group " <sup>1</sup> PAn" (parameters relative to the user interface)         Description         Range         Def.         Note           38         AdE         Shift value for the shift         OFF9999         2         1	33	tcr1			20.0	
35         tcr2         Cycle time of 2.rEG         0.1 ÷ 130.0 sec.         10.0 sec.           36         rS         Manual reset         -100.0÷100.0 %         0.0 %           37         SLor         Gradient of ramp: InF= Ramp not active         0.00 ÷ 99.99 / InF         InF           Group " <sup>1</sup> PAn" (parameters relative to the user interface)         Par.         Description         Range         Def.         Note           38         AdE         Shift value for the shift         OFF9999         2         2	34	Drat		Sec.	1 00	
Sec.     sec.       36     rS     Manual reset     -100.0÷100.0     0.0       37     SLor     Gradient of ramp: InF= Ramp not active     0.00÷99.99     InF       Group " <sup>1</sup> PAn" (parameters relative to the user interface)     Par.     Description     Range     Def.     Note       38     AdE     Shift value for the shift     OFF9999     2						
36       rS       Manual reset       -100.0÷100.0       0.0         37       SLor       Gradient of ramp:       0.00÷99.99       InF         37       SLor       Gradient of ramp:       / InF unit/min.       InF         Group " <sup>1</sup> PAn" (parameters relative to the user interface)       Par.       Description       Range       Def.       Note         38       AdE       Shift value for the shift       OFF9999       2       2		.012			. 0.0	
37     SLor     Gradient of ramp: InF= Ramp not active     0.00 ÷ 99.99 / InF unit/min.     InF       Group " <sup>1</sup> PAn" (parameters relative to the user interface)       Par.     Description     Range     Def.     Note       38     AdE     Shift value for the shift     OFF9999     2	26		Manual reast	100.0.100.0	0.0	
37       SLor       Gradient of ramp: InF= Ramp not active       0.00 ÷ 99.99 / InF unit/min.       InF         Group " <sup>1</sup> PAn" (parameters relative to the user interface)         Par.       Description       Range       Def.       Note         38       AdE       Shift value for the shift       OFF9999       2	100	rs	Iniditudi teset		0.0	
InF= Ramp not active       / InF unit/min.         Group " <sup>1</sup> PAn" (parameters relative to the user interface)         Par.       Description       Range       Def.       Note         38       AdE       Shift value for the shift       OFF9999       2	37	SLor	Gradient of ramp:	0.00 ÷ 99.99	InF	
Group " <sup>1</sup> PAn" (parameters relative to the user interface)Par.DescriptionRangeDef.Note38AdEShift value for the shiftOFF99992			InF= Ramp not active	/ InF unit/min.		
38 AdE Shift value for the shift OFF9999 2	Group " <sup>1</sup> PAn" (parameters relative to the user interface)					
				Range		Note
	38	AdE		OFF9999	2	
			index functioning			

#### 6 - PROBLEMS, MAINTENANCE AND GUARANTEE

#### 6.1 - ERROR SIGNALLING

Error	Reason	Action	
	Probe interrupted Verify the corre		
uuuu	The measured variable is under the probe's limits (under-range)	and instrument and then verify the correct	
0000	The measured variable	functioning of the probe	

	is over the probe's limits (over-range)		
ErAt	Auto-tuning not possible	Push key "P" in order to make the error message disappear. Once the error has been found, try to repeat the auto-tuning.	
noAt	Auto-tuning not finished within 12 hours	Check the functioning of probe and actuator and try to repeat the auto-tuning.	
ErEP	Possible anomaly of the EEPROM memory	Push key "P"	

In error conditions, the instrument provides an output power as programmed on par "OPE" and activates the alarm, if the relative parameter "AL1i" have been programmed = yES.

#### 6.2 - CLEANING

We recommend cleaning of the instrument with a slightly wet cloth using water and not abrasive cleaners or solvents which may damage the instrument.

#### 6.3 - GUARANTEE AND REPAIRS

The instrument is under warranty against manufacturing flaws or faulty material, that are found within 12 months from delivery date. The guarantee is limited to repairs or to the replacement of the instrument. The eventual opening of the housing, the violation of the instrument or the improper use and installation of the product will bring about the immediate withdrawal of the warranty's effects.

In the event of a faulty instrument, either within the period of warranty, or further to its expiry, please contact our sales department to obtain authorisation for sending the instrument to our company. The faulty product must be shipped to TECNOLOGIC with a detailed description of the faults found, without any fees or charge for Tecnologic, except in the event of alternative agreements.

#### 7 - TECHNICAL DATA

#### 7.1 – ELECTRICAL DATA

<u>Power supply:</u> 24 VAC/VDC, 100.. 240 VAC +/- 10% <u>Frequency AC:</u> 50/60 Hz

Power consumption: 4 VA approx.

Input/s: 1 input for temperature probes: tc J,K,S ; infrared sensors TECNOLOGIC IRS J e K; RTD Pt 100 IEC; PTC KTY 81-121 (990  $\Omega$  @ 25 °C); NTC 103AT-2 (10K $\Omega$  @ 25 °C) or mV signals 0...50 mV, 0...60 mV, 12 ...60 mV or normalized signals 0/4...20 mA, 0..1 V, 0/1...5 V , 0/2...10 V.

Normalized signals input impedance: 0/4..20 mA: 51  $\Omega;~mV$  and V: 1  $M\Omega$ 

<u>Output/s:</u> Up to 2 outputs. Relay SPST-NO (8A-AC1, 3A-AC3 250 VAC,1/2HP 250VAC, 1/3HP 125 VAC); or in tension to drive SSR (8mA/ 8VDC).

Auxiliary supply output: 12 VDC / 20 mA Max.

Electrical life for relay outputs: 100000 operat.

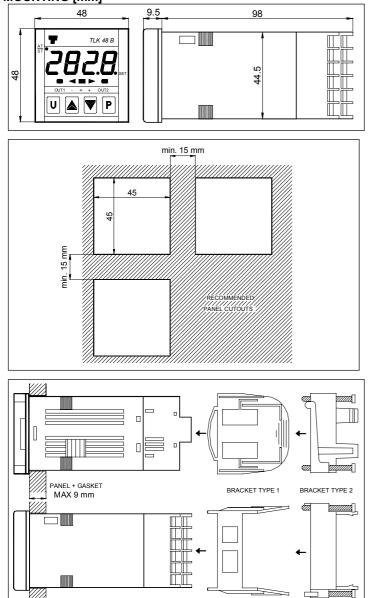
Installation category: II Measurement category: I

Protection class against electric shock: Class II for Front panel Insulation: Reinforced insulation between the low voltage part (power supply and relay outputs) and front panel; Reinforced insulation between the low voltage section (Supply and relay outputs) and the extra low voltage section (input, SSR outputs); Reinforced between power supply and relays; No insulation between input and SSR outputs.

#### 7.2 – MECHANICAL DATA

<u>Housing:</u> Self-extinguishing plastic, UL 94 V0 <u>Dimensions:</u> 48 x 48 mm DIN, depth 98 mm <u>Weight:</u> 150 g approx. <u>Mounting:</u> Flush in panel in 45 x 45 mm hole <u>Connections:</u> 2 x 1 mm<sup>2</sup> screw terminals block <u>Degree of front panel protection :</u> IP 54 mounted in panel with gasket Pollution situation: 2 Operating temperature: 0 ... 50 °C Operating humidity: 30 ... 95 RH% without condensation Storage temperature: -10 ... +60 °C

#### 7.3 - MECHANICAL DIMENSIONS, PANEL CUT-OUT AND MOUNTING [mm]



#### 7.4 - FUNCTIONAL FEATURES

Control: ON/OFF, single and double action PID <u>Measurement range: according to the used probe (see range table)</u> Display resolution: according to the probe used 1/0,1/0,01/0,001 Overall accuracy: +/- (0,5 % fs + 1 digit) ; tc S: +/- (1 % fs + 1 digit) Max cold junction compensation drift (in tc) : 0,1 °C/°C with e: UNAVAILABLE CODES operating temperature 0 ... 50 °C after warm-up of 20 min. Sampling rate: 130 ms. Display: 4 Digit Red h 12 mm Compliance: ECC directive EMC 2004/108/CE (EN 61326), ECC directive LV 2006/95/CE (EN 61010-1) Approvals: C-UL (file n. E206847)

#### 7.5 - MEASURING RANGE TABLE

INPUT	"dP" = 0	"dP"= 1, 2, 3
tc J	0 1000 °C	
"SEnS" = J	32 1832 °F	
tc K	0 1370 °C	
"SEnS" = CrAl	32 2498 °F	

tc S	0 1760 °C	
"SEnS" = S	32 3200 °F	
Pt100 (IEC)	-200 850 °C	-199.9 850.0 °C
"SEnS" = Pt1	-328 1562 °F	-199.9 999.9 °F
PTC (KTY81-121)	-55 150 °C	-55.0 150.0 °C
"SEnS" = Ptc	-67 302 °F	-67.0302.0 °F
NTC (103-AT2)	-50 110 °C	-50.0 110.0 °C
"SEnS" = ntc	-58 230 °F	-58.0 230.0 °F
020 mA		
"SEnS" = 0.20		
420 mA		
"SEnS" = 4.20		
0 50 mV		
"SEnS" = 0.50		
0 60 mV		
"SEnS" = 0.60		-199.9 999.9
12 60 mV		
"SEnS" = 12.60	-1999 9999	-19.99 99.99
0 1 V		
"SEnS" = 0.1		-1.999 9.999
0 5 V		
"SEnS" = 0.5 1 5 V		
1 5 V "SEnS" = 1.5		
0 10 V		
0 10 V "SEnS" = 0.10		
2 10 V		
"SEnS" = 2.10		
SEIIS - 2.10		

#### 7.6 - INSTRUMENT ORDERING CODE

#### TLK48 a b c d e ff B

#### a : POWER SUPPLY

L = 24 VAC/VDCH = 100... 240 VAC

#### **b** : INPUT

C = thermocouples (J, K, S, I.R), mV, thermoresistances (Pt100) **E** = thermocouples (J, K, S, I.R.), mV, thermistors (PTC, NTC)

I = normalized signals 0/4..20 mA V = normalized signals 0..1 V, 0/1..5 V, 0/2..10 V.

#### c: OUTPUT OUT1

R = Relay O = VDC for SSR

#### d : OUTPUT OUT2

R = Relay **O** = VDC for SSR - = None

ff : SPECIAL CODES

# **TLK 48 B PASSWORD = 381**