## ELECTRONIC ROTARY GEAR MOTOR SERIES SED (AR2...SE...)

## Installation and Operating Instructions

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1.1 Installation must be performed by properly trained and experienced service technicians only.
1.2 Do not attempt to turn the gear motor shaft by hand or by means of a wrench, otherwise damage to the gear train may occur.
1.3 Before servicing make sure that power supply to the gear motor has been disconnected.
1.4 Check carefully all instructions before operating the gear motor automatically.
1.5 Each gear motor is supplied with a label fixed under the conduit plug.
1.6 The main servicing data and technical features of the gear motor are indicated on the label. All technical functions are specified in the relative technical data sheet.
1.7 Before installing or operating the gear motor make sure that its employment complies with the range of performances reported on the label.
1.8 When positioning the gear motor consider that it must be easily accessible in order to be able to perform wiring and adjustment of endswitches.
1.9 The gear motor can be installed in any location included in the range of electrical protection IP54, except where acid fumes or other deteriorating vapour might attack its metal parts or where gas leaks or explosive vapours are present in the atmosphere. In environments with high salt percentage, the fastening screws should be zinc or cadmium plated, not made of brass or stainless steel.

| Body and cover | die-cast aluminium |
| :---: | :---: |
| Output torque | $4 \div 20 \mathrm{Nm}$ |
| Maintaining torque | $4 \div 20 \mathrm{Nm}$ |
| Stroking time | 7,5 $\div 60$ seconds for $90^{\circ}$ at 50 Hz |
| Output shaft | $\varnothing 12 \mathrm{~mm}$ with $\square 9,5 \mathrm{~mm}$ |
| Installation | in any position |
| Ambient temperature | $-10 \div 60{ }^{\circ} \mathrm{C}$ |
| Weight | $\sim 2,5 \mathrm{~kg}$ |
| Main supply | $24 \mathrm{Vac} / 50-60 \mathrm{~Hz}$ <br> on request with transformer 230 Vac or $115 \mathrm{Vac} / 24 \mathrm{Vac} 50-60 \mathrm{~Hz}$ |
| Adsorbed power | 7 VA |
| Input signal | according to model [refer to § 10] |
| Input signal impedance | according to model [refer to § 10] |
| Local control station | Auto/Manual and Open/Close/Stop |
| Rating of el. contacts |  |
| limit and auxiliary switches | 0,5 A / 48 Vdc and Vac |
| Enclosure Rating | IP 54 according to IEC 529 |
| Duty cycle | continuous 100\% |
| Conduit knockouts | $2 \times \mathrm{Pg} 13,5$ |

## 3 INSTALLATION

3.1 The gear motor must be positioned so that the square shaft [POWER END] is turned towards the device to be put in motion.
3.2 If no other adjustment of the rotation angle is expressly requested, the gear motor is always supplied from the factory with standard adjustment of endswitches for a $90^{\circ}$ rotation.
3.3 The square shaft on the POWER END side is positioned in the factory as shown in picture 1.


Picture n. 1

## 4 ELECTRIC CONNECTIONS

4.1 After having installed the gear motor and before fastening it mechanically to the device to be controlled, proceed with wiring and earthling.
4.2 The wiring diagrams are reported both in the attached technical bulletin and on the plate inside the cover.
4.3 Warning: before servicing make sure that power supply is disconnected by means of the two-pole-switch [phase and neutral]. In case of non-observance, damages to people and to the equipment may occur.
4.4 External supply voltage transformer with load $>15 \mathrm{VA}$ protected against overloading.
4.5 To accede to the internal wiring terminal board remove the cover by loosening the 4 fastening screws.
4.6 On the frame of the gear motor are located 2 threaded holes for the fitting of the conduit plug PG 13.5 and 2 extra $1 / 4$ " holes [on request] if pressurizing of the motor is requested.
4.7 All wires must comply with local prescriptions and, in any case, their section must be ranging between 1 and $1.5 \mathrm{~mm}^{2}$.
4.8 Connection piping recommended HO7V-U...G $1.5 \mathrm{~mm}^{2}$.
4.9 The wiring diagrams show the gear motor at end position closed $\left[0^{\circ}\right]$.

Warning An immediate accident may occur onto circuit board due to wrong wiring. Check it carefully before servicing.
4.10 The auxiliary microswitches are single-pole double through and are voltage-free.
4.11 The auxiliary microswitches rating is 0,5 A / 48 Vdc e Vac.
4.12 Make sure that power supply and system frequency match to the values indicated on the gear motor's plate.

WARNING Transformer power supply must be separated from that of the gear motor.
4.13 The low-tension signalling cables [tension lower than 48V] must be laid separately from the higher-tension-conduits [tension higher than 48V]. In case they are laid in a single channel, screened cables must be used.


Valid only for SED...SE1, SE2, SE7 e SE8

### 5.1 Endswitches

As already reported in chapter 3 paragraph 3.2, the electronic gear motor is supplied by the factory with adjustment foreseen for a maximum $90^{\circ}$ rotation angle. On request is also available a circuit board with SPAN features, i.e. Starting Point and WORKING RANGE regulation.

### 5.2 Auxiliary Microswitches

5.2.1 The gear motor is supplied with 2 auxiliary microswitches that can be adjusted in any position of the rotation angle.
5.2.2 For cam adjustment, use the proper key supplied with the gear motor equipment and installed inside.
5.2.3 Use the key by the right side, introducing the pin into one of the holes on the sides of the blue cam "S3" or "S4" according to the need and lift it to required angle position [Picture 2].
5.2.4 By the blue cam in the rearmost position, at first use the lever on its curved side to move the blue cam to a more suitable position to perform adjustment.
5.2.5 Cam adjustment is possible in both directions and along the whole rotation angle of the camshaft.


Picture n. 2
5.2.6 Remove the key before servicing.
5.2.7 Run the gear motor for a few cycles making sure that the right cam adjustment has been achieved.
5.2.8 Once all adjustments have been carried out, return the key inside the gear motor and reinstall the cover by fastening the 4 screws.
5.2.9 Reinstall the control lever system of the gear motor and test the whole system works properly.

### 5.3 Setting working range

One of the features of actuators series SED...-SE, is the possibility to reduce the working range of the actuator, i.e. contract the working range from $90^{\circ}$ to $45^{\circ}$ by utilizing the whole input signal $4-20 \mathrm{~mA}$ or $0-10 \mathrm{~V}$.

In order to limit the working range follow these steps:

1. Turn the trimmer screw (shown in the picture) counter-clockwise for about 20 turns, the screw in endless.

2. Supply power and set the input signal to the maximum value (i.e. 20 mA or 10 V ) and the actuator will turn :

- with rotation clockwise (dip-switch no. 1 on the right handside) up to $45^{\circ}$. Then the actuator will rotate by $45^{\circ}$ between $45^{\circ}$ and $0^{\circ}$ with the entire signal $4-20 \mathrm{~mA}$ or $0-10 \mathrm{~V}$.
- with rotation counter-clockwise (dip-switch no. 1 on the left handside) up to $90^{\circ}$. Then the actuator will rotate by $45^{\circ}$ between $90^{\circ}$ up to $45^{\circ}$ with the entire signal $4-20 \mathrm{~mA}$ or $0-10 \mathrm{~V}$.

3. In order to widen the working range it is possible to set any degree of angle between $45^{\circ}$ and $90^{\circ}$ with a fine regulation.
Supply power and set the input signal to the maximum value (i.e. 20 mA or 10 V ) and turn the trimmer screw (as shown in the picture) clockwise, the actuator will extend his working range by approx one degree for each turn of the screw. Once you set the desired working range, the actuator will rotate within this angle (i.e. $60^{\circ}$ ) with the entire input signal $4-20 \mathrm{~mA}$ or $0-10 \mathrm{~V}$.

The gear motors are equipped with control station, which works as follows:
6.1 Connect phase L1 to terminal \# 1 and neutral N to terminal \# 2.
6.2 Set the AUTO/MAN dip-switch on manual position [ON] at the left.
6.3 A red LED will light up to show the manual working way.
6.4 Push red knobs - / + to rotating the shaft clockwise or counterclockwise.
6.5 Re-set the dip-switch onto automatic way [pos. 1 on the right] when manual calibration is finished. the red LED will light off.


Picture n. 3

## 7 PROPORTIONAL OPERATION

7.1 All adjustments are already set at factory. Hence, it is recommended to avoid any intervention on cams and potentiometer.
7.2 Warning: potentiometer is installed for card balancing purposes ONLY. Consequently, it is not to be used.

## 8 MAINTENANCE AND CHECKS

### 8.1 Maintenance

8.1.1 The gear motor does not require any particular current maintenance.
8.1.2 The gear motor does not require any lubrication since the gear box is lubricated at factory.
8.1.3 Avoid any on field reparation.
8.1.4 Do not disassemble any internal part of the gear motor. In case of non-functioning, after having performed all possible checks on field, the gear motor must be returned to the factory for any possible repair. Any replacement must be carried out by qualified technicians only.

## 8.2 <br> Сhecks

After installation and adjustment of the control lever system check that switch and wiring of the circuit are correct.
Check that the rotary gear motor duly controls the device it is meant for.
Check that the gear motor runs in accordance with the given manual input.
Check that the gear motor, the lever system and the controlled device are mechanically connected in a correct and safe way.
Check that the levers' movements occur smoothly without jamming or blocking due to other objects.

## 9 REPLACEMENT

In case replacement of the gear motor is necessary, proceed as follows:

- disconnect power supply from the motor
- remove the gear motor's cover
- disconnect electric wiring
- remove the levers between the gear motor and the controlled device
- install the new gear motor proceeding as per instructions given in the foregoing chapters


## 10 ELECTRONIC CONFIGURATION

The digital electronic board mounted on gear actuator enable to set various features / options, like rotation direction, resolution, type of input control signal and impedance.
warning For each model there is a specific electronic board, with its own specification in hardware and software.

The desired configuration can be obtained by setting dip-switch of the electronic board on the right or left hand side, according to the below indicated schemes.

Dip-switches are located under the paperboard panel over the horizontal board. Lift the rectangular paperboard to access the dip-switches
10.1 Electronic Configuration SED...SE1 Input signal 0-10V Output signal 0-10V

| DIP SWITCH POSITION |  |  |
| :---: | :---: | :---: |
| DIP <br> SwITCH | DIP Switch On LEFT <br> OFF | DIP SwITCH ON RIGHT <br> ON |
| $\mathbf{1}$ | Clockwise Rotation <br> (from Power End side) | Counter-Clockwise Rotation <br> (from Power End side) |
| $\mathbf{2}$ | Low Resolution 125 steps | High Resolution 200 steps |

** For other setting please look here below:

3
4


STANDARD setting, Input and Output signal always aligned. For example 2 V input e 2 V output.

3
4


3
4


DS-3 turned ON and DS-4 turned OFF. Actuator rotates for $90^{\circ}$ with Mid-Low Input Signal. For example 0-5V with rotation of $90^{\circ}$.

3
4


REVERSE OUTPUT (only for counter-clockwise rotation). For example 2V Input signal and 8V Output Signal.

DS-3 turned OFF and DS-4 turned ON. Actuator rotates for $90^{\circ}$ with Mid-High Input Signal. For example 5-10V with rotation of $90^{\circ}$.
10.2 Electronic Configuration SED...SE2 Input signal 4-20 mA or 0-10V Output SIGNAL 0-10V

| DIP SWITCH POSITION |  |  |
| :---: | :---: | :---: |
| DIP <br> SwITCH | DIP Switch On LEFT <br> OFF | DIP SwITCH ON RIGHT <br> ON |
| $\mathbf{1}$ | Clockwise Rotation <br> (from Power End side) | Counter-Clockwise Rotation <br> (from Power End side) |
| $\mathbf{2}$ | Low Resolution 125 steps | High Resolution 200 steps |

** For other setting please look here below:


STANDARD setting, Input and Output signal always aligned. For example 2 V input e 2 V output.

3
4


REVERSE OUTPUT (only for counter-clockwise rotation). For example 2V Input signal and 8V Output Signal.

3
4


DS-3 turned ON and DS-4 turned OFF. Actuator rotates for $90^{\circ}$ with Mid-Low Input Signal. For example $0-5 \mathrm{~V}$ with rotation of $90^{\circ}$.

3
4


DS-3 turned OFF and DS-4 turned ON. Actuator rotates for $90^{\circ}$ with Mid-High Input Signal. For example 5-10V with rotation of $90^{\circ}$.

| DIP SWITCH POSITION |  |  |
| :---: | :---: | :---: |
| DIP <br> SWITCH | DIP SwITCH ON LEFT <br> OFF | DIP SwITCH ON RIGHT <br> ON |
| $\mathbf{1}$ | Clockwise Rotation <br> (from Power End side) | Counter-Clockwise Rotation <br> (from Power End side) |
| $\mathbf{2}$ | Low Resolution 125 steps | High Resolution 200 steps |

** For special setting please look here below:


DS-3 turned ON and DS-4 turned OFF. Actuator rotates for $90^{\circ}$ with Mid-Low Input Signal. For example $0-5 \mathrm{~V}$ with rotation of $90^{\circ}$.

DS-3 turned OFF and DS-4 turned ON. Actuator rotates for $90^{\circ}$ with Mid-High Input Signal. For example 5-10V with rotation of $90^{\circ}$.
10.4 Electronic Configuration SED...SE5 Input signal 4-20 mA

| DIP SWITCH POSITION |  |  |
| :---: | :---: | :---: |
| DIP <br> SwITCH | DIP Switch On LEFT <br> OFF | DIP Switch ON RIGHT <br> ON |
| $\mathbf{1}$ | Clockwise Rotation <br> (from Power End side) | Counter-Clockwise Rotation <br> (from Power End side) |
| $\mathbf{2}$ | Low Resolution 125 steps | High Resolution 200 steps |

** For special setting please look here below:

3
4


DS-3 turned ON and DS-4 turned OFF. Actuator rotates for $90^{\circ}$ with Mid-Low Input Signal. For example 4-12 mA with rotation of $90^{\circ}$.

3
4


DS-3 turned OFF and DS-4 turned ON. Actuator rotates for $90^{\circ}$ with Mid-High Input Signal. For example 12-20 mA with rotation of $90^{\circ}$.

## DIP SWITCH POSITION

| DIP <br> SwITCH | DIP Switch On LEFT <br> OFF | DIP Switch ON RIGHT <br> ON |
| :---: | :---: | :---: |
| $\mathbf{1}$ | Clockwise Rotation <br> (from Power End side) | Counter-Clockwise Rotation <br> (from Power End side) |
| $\mathbf{2}$ | Low Resolution 125 steps | High Resolution 200 steps |

** For other setting please look here below:

3
4


STANDARD setting, Input and Output signal always aligned. For example 2 V input e 2 V output.

3
4


REVERSE OUTPUT (only for counter-clockwise rotation). For example 2V Input signal and 8V Output Signal.

3
4


DS-3 turned ON and DS-4 turned OFF. Actuator rotates for $90^{\circ}$ with Mid-Low Input Signal. For example 0-5V with rotation of $90^{\circ}$.

3
4


DS-3 turned OFF and DS-4 turned ON. Actuator rotates for $90^{\circ}$ with Mid-High Input Signal. For example 5-10V with rotation of $90^{\circ}$.
10.6 Electronic Configuration SED...SE8 Input signal 4-20mA Output Signal 4-20mA

| DIP SWITCH POSITION |  |  |
| :---: | :---: | :---: |
| DIP SWITCH | Dip Switch On LEFT OfF | Dip Switch On RIGHT |
| 1 | Clockwise Rotation (from Power End side) | Counter-Clockwise Rotation (from Power End side) |
| 2 | Low Resolution 125 steps | High Resolution 200 steps |
| 3 | Standard setting (**) INPUT and OUTPUT always aligned |  |
| 4 | Standard setting (**) INPUT and OUTPUT always aligned |  |
| 5 | N.A. | Input Signal 4-20 mA |
| 6 | N.A. | DS-6 MUST be turned ON |

** For other setting please look here below:

3
4


STANDARD setting, Input and Output signal always aligned. For example 2 V input e 2 V output.

3
4


3
4


REVERSE OUTPUT (only for counter-clockwise rotation). For example 2V Input signal and 8V Output Signal.

DS-3 turned ON and DS-4 turned OFF. Actuator rotates for $90^{\circ}$ with Mid-Low Input Signal. For example $0-5 \mathrm{~V}$ with rotation of $90^{\circ}$.

3
4


DS-3 turned OFF and DS-4 turned ON. Actuator rotates for $90^{\circ}$ with Mid-High Input Signal. For example 5-10V with rotation of $90^{\circ}$.

This manual can be amended without any obligation of notice

